

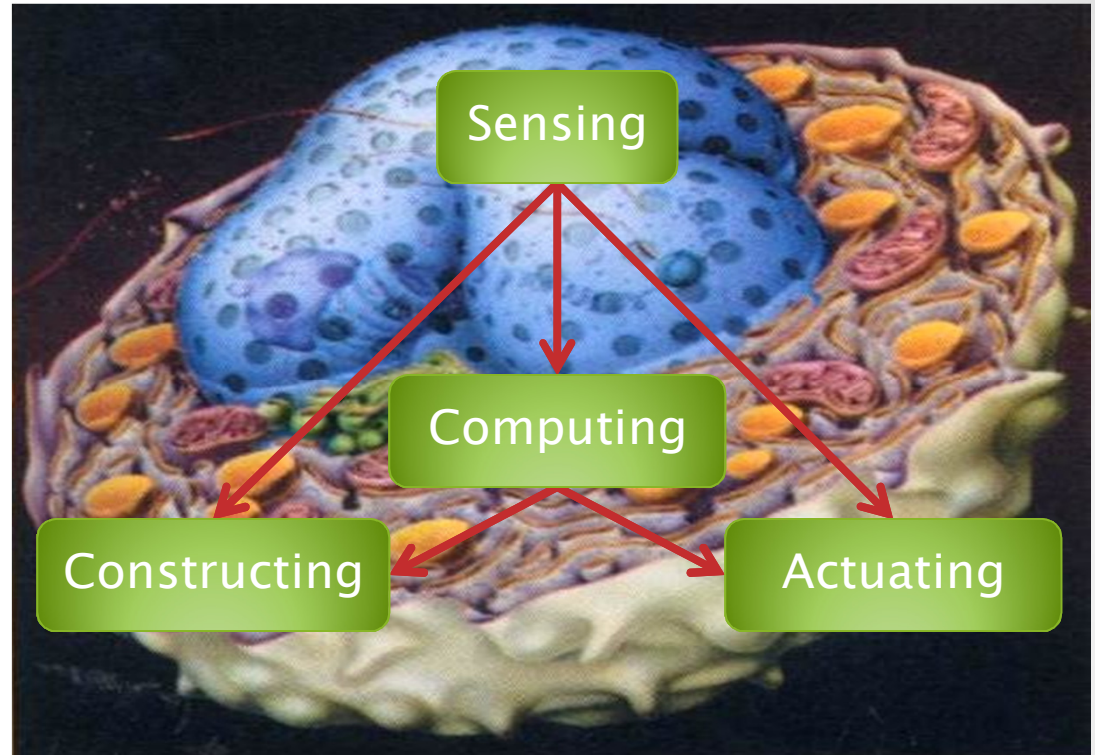
# Two-Domain DNA Strand Displacement

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Microsoft Research

Frontiers of Multidisciplinary Research, Exeter, 2010-09-21  
<http://lucacardelli.name>

# Nanoscale Engineering

- Sensing
  - Reacting to forces
  - Binding to molecules
- Actuating
  - Releasing molecules
  - Producing forces
- Constructing
  - Chassis
  - Growth
- Computing
  - Signal Processing
  - Decision Making



Nucleic Acids can do all this.  
And interface to **biology**.  
And are **programmable**.

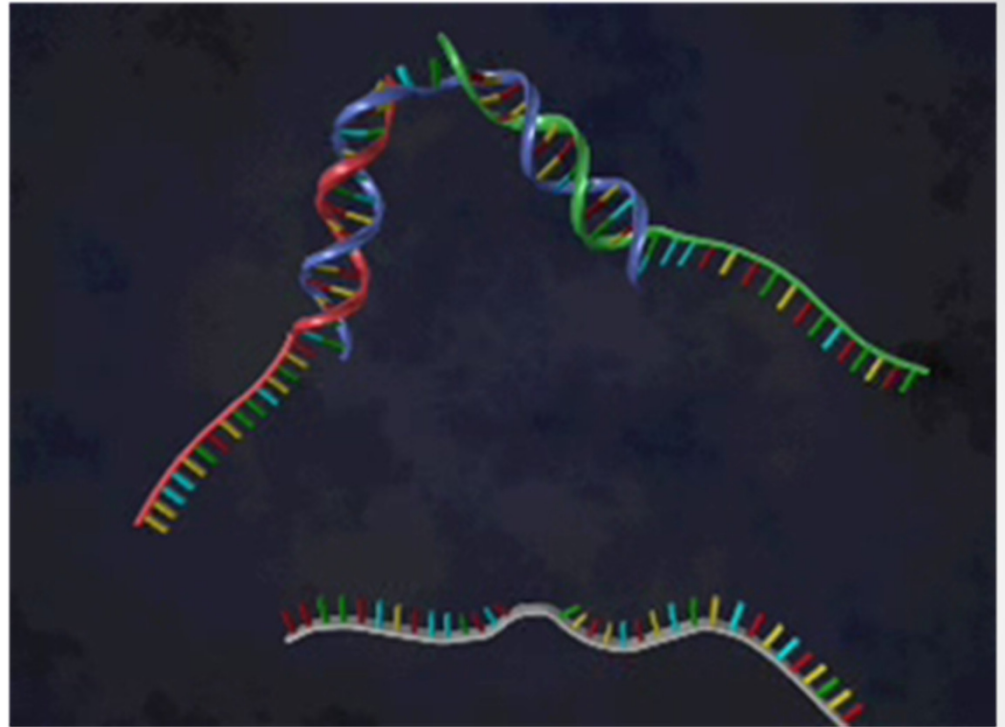
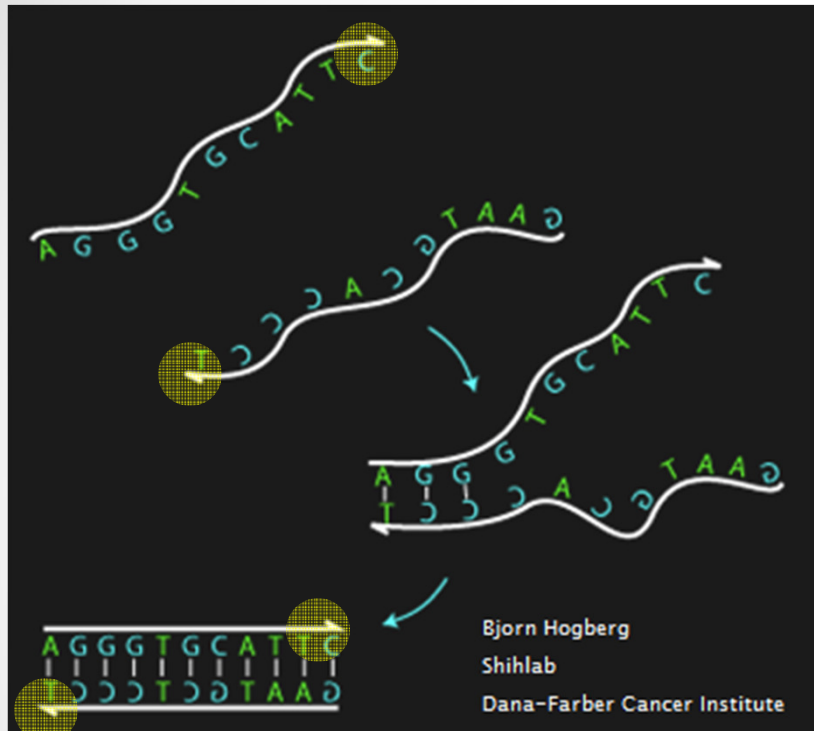
# Nanoscale Networks

- Building artificial networks
  - For sensing and control at the molecular level
  - Applications to materials, computing, and medicine
- Using biological materials
  - Biological = programmable molecules
  - Proteins are hard to design
  - We can do better with nucleic acids
- Learning by construction
  - What is easy/hard to do with these materials?

# Strand Displacement Basics

...

# DNA Hybridization



- Strands with opposite orientation and complementary base pairs stick to each other (Watson-Crick duality).
- This is all we are going to use
  - We are not going to exploit DNA replication, transcription, translation, restriction and ligation enzymes, etc., which enable other classes of tricks.

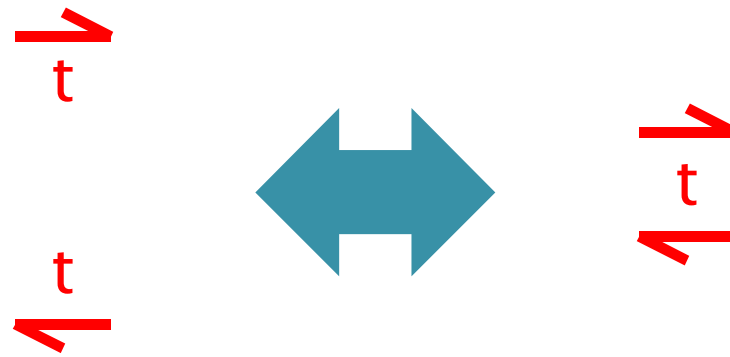
# Domains

- Subsequences on a DNA strand are called **domains**.
- PROVIDED they are “independent” of each other.



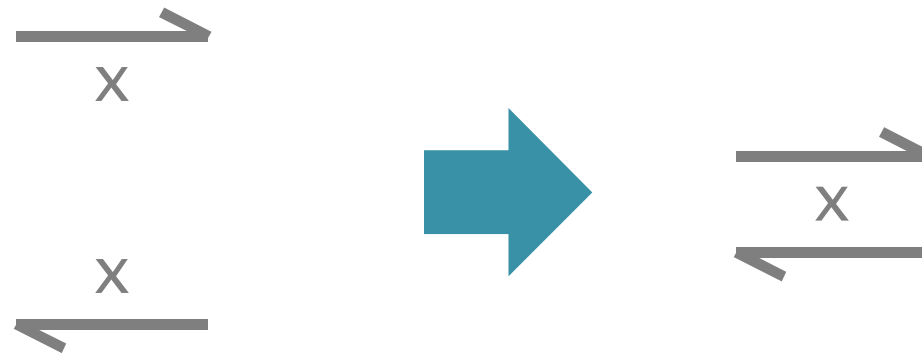
- I.e., differently named domains must not hybridize:
  - With each other
  - With each other's complement
  - With subsequences of each other
  - With concatenations of other domains (or their complements)
  - Etc.
- Choosing domains (subsequences) that are suitably independent is a tricky issue that is still somewhat of an open problem (with a vast literature). But it can work in practice.

# Short Domains



Reversible Hybridization

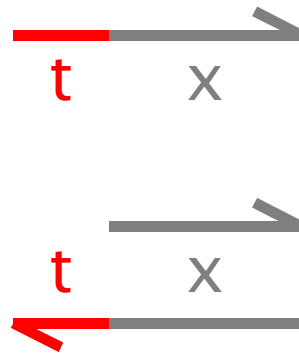
# Long Domains



Irreversible Hybridization

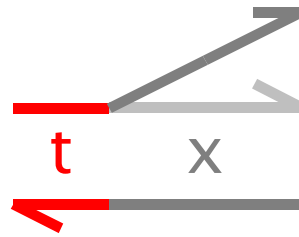


# Strand Displacement



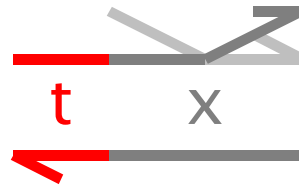
“Toehold Mediated”

# Strand Displacement



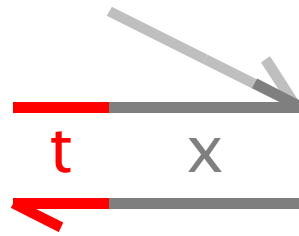
Toehold Binding

# Strand Displacement



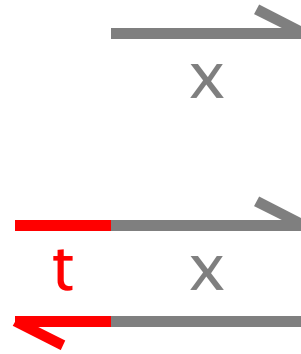
Branch Migration

# Strand Displacement



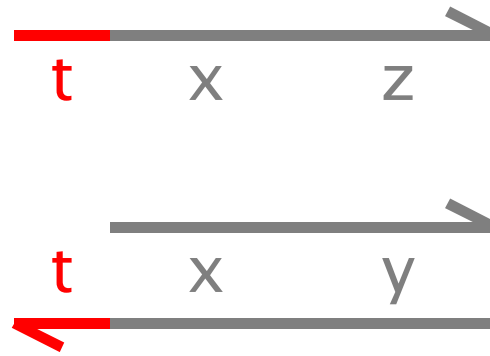
Displacement

# Strand Displacement

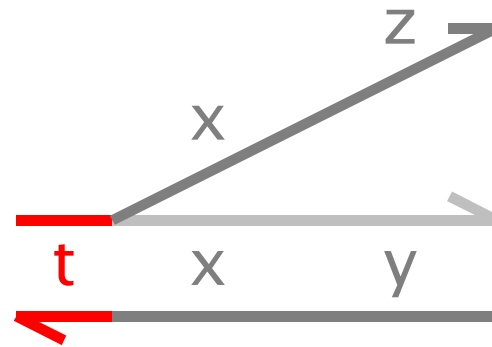


Irreversible release

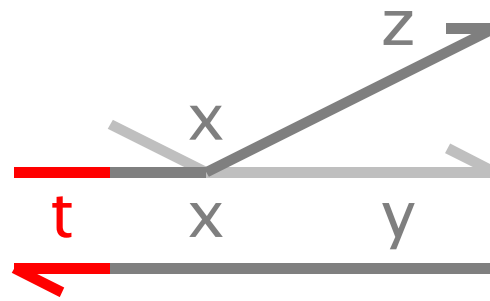
# Bad Match



# Bad Match

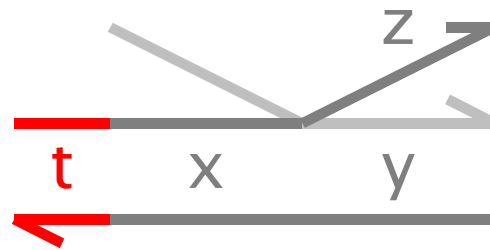


# Bad Match





# Bad Match



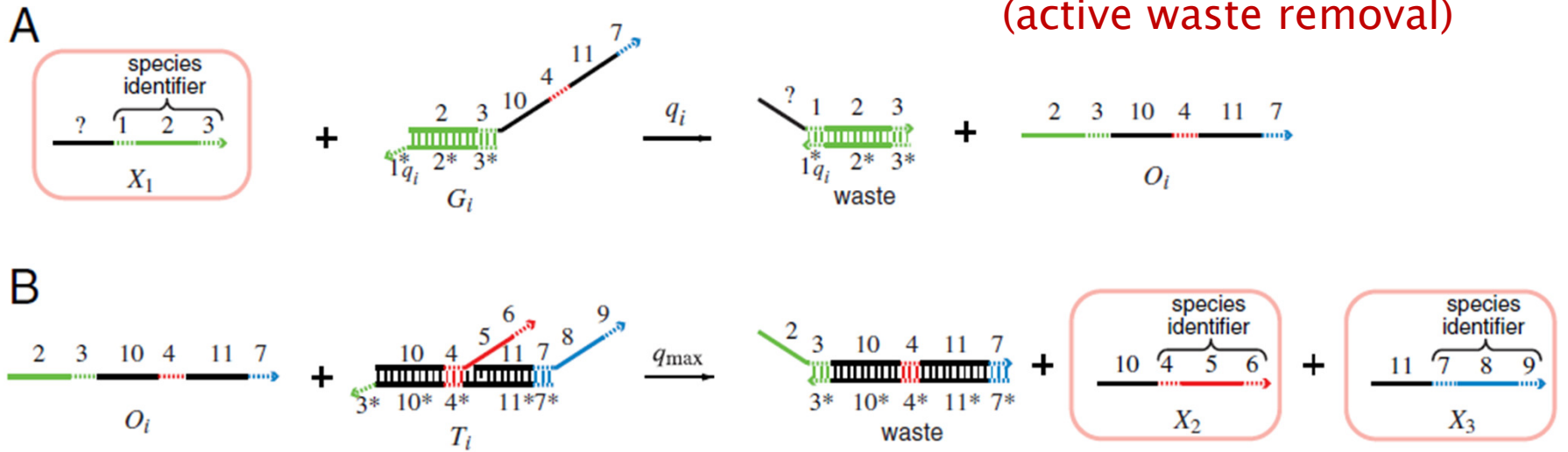
Cannot proceed  
Hence will undo

# Signals & Gates

...

# Four-Domain Architecture

No “garbage collection”  
(active waste removal)



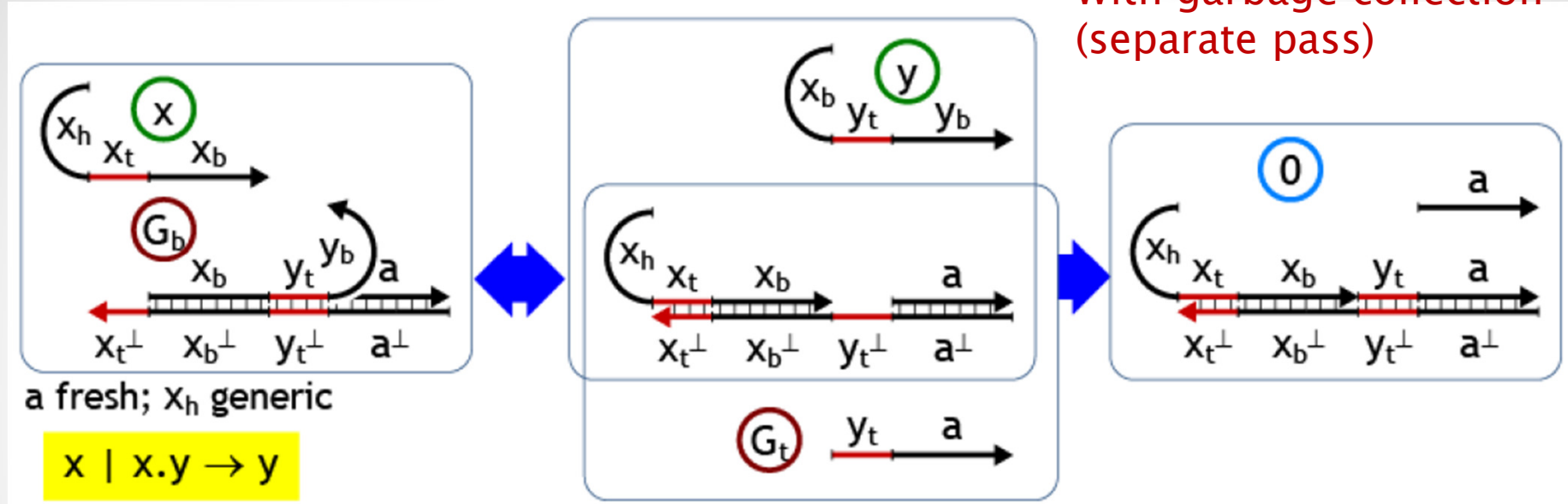
## DNA as a universal substrate for chemical kinetics

David Soloveichik<sup>a,1</sup>, Georg Seelig<sup>a,b,1</sup>, and Erik Winfree<sup>c,1</sup>

PNAS | March 23, 2010 | vol. 107 | no. 12 | 5393–5398

# Three-Domain Architecture

With garbage collection  
(separate pass)



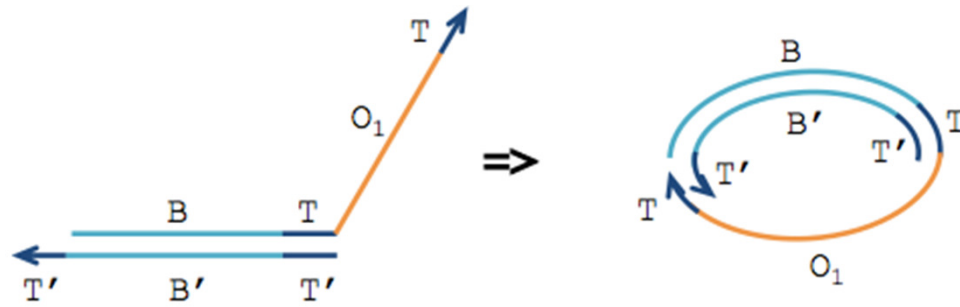
## Strand Algebras for DNA Computing

Luca Cardelli

DNA Computing and Molecular Programming.

15th International Conference, DNA 15, LNCS 5877, Springer 2009, pp 12-24.

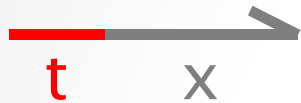
# “Lulu’s Trouble”



(from D.Soloveichik)

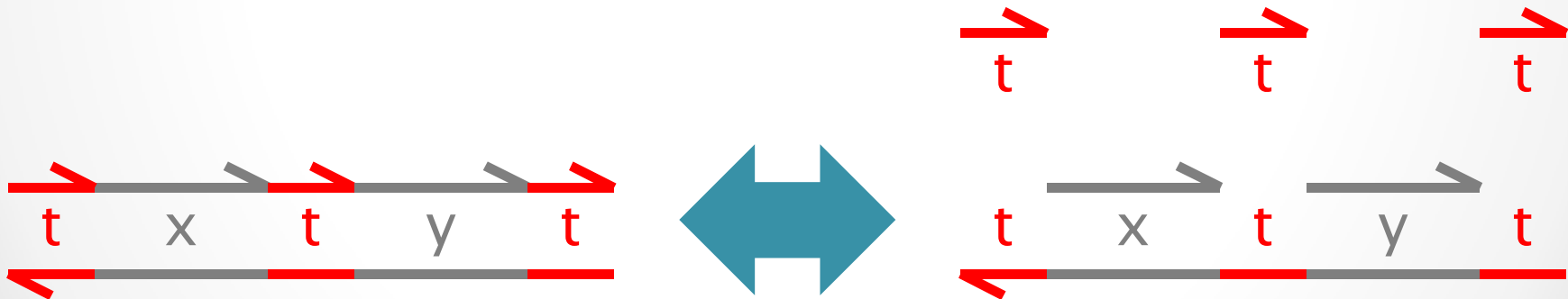
# Two-Domain Architecture

- Signals: 1 toehold + 1 recognition region

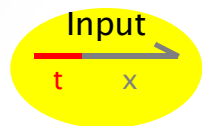


Garbage collection  
“built into” the gates

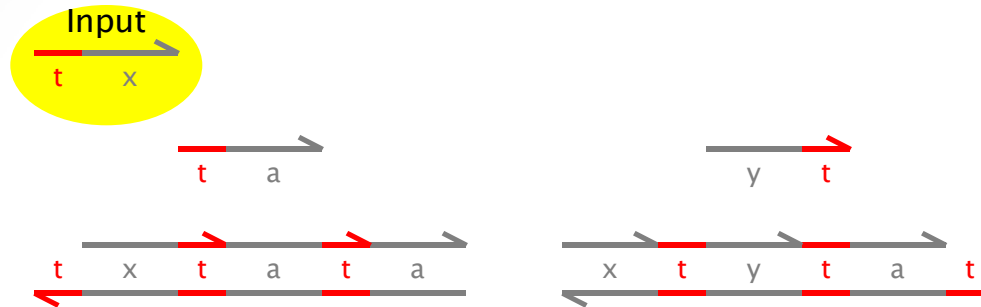
- Gates: “top-nicked double strands”  
(or equivalently double strands with open toeholds)



# Transducer $x \rightarrow y$



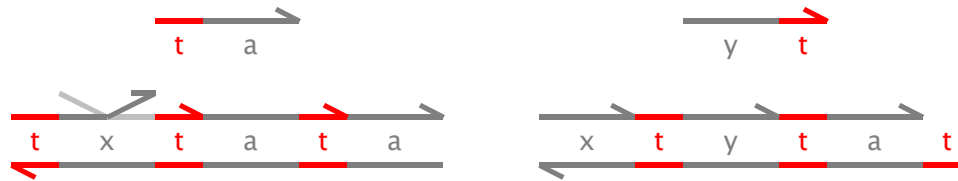
# Transducer $x \rightarrow y$



**ta** is a *private* signal (a different 'a' for each xy pair)

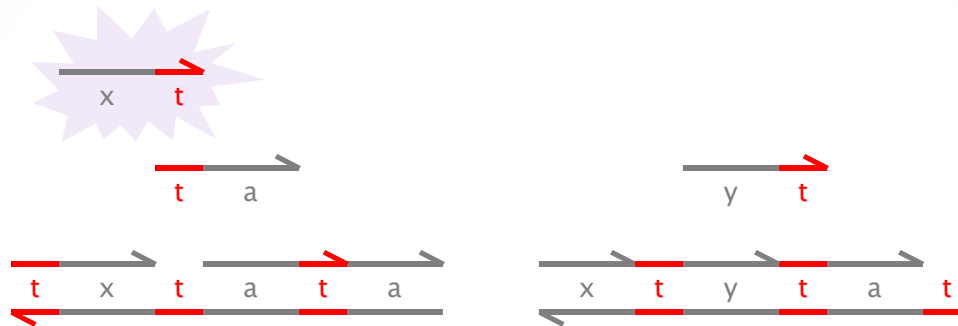


# Transducer $x \rightarrow y$

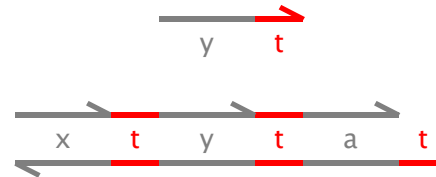
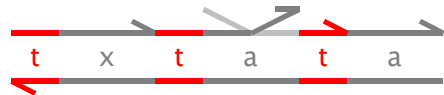
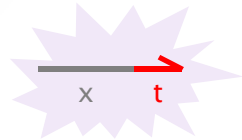


# Transducer $x \rightarrow y$

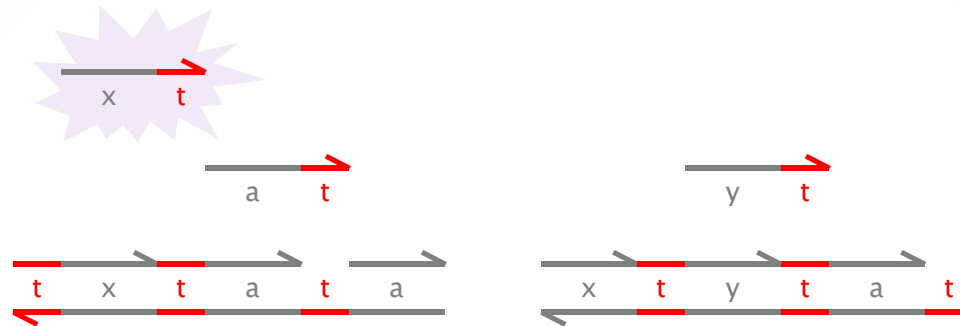
Active  
waste



# Transducer $x \rightarrow y$

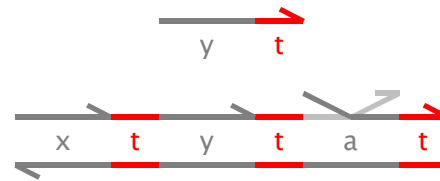
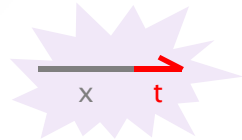


# Transducer $x \rightarrow y$

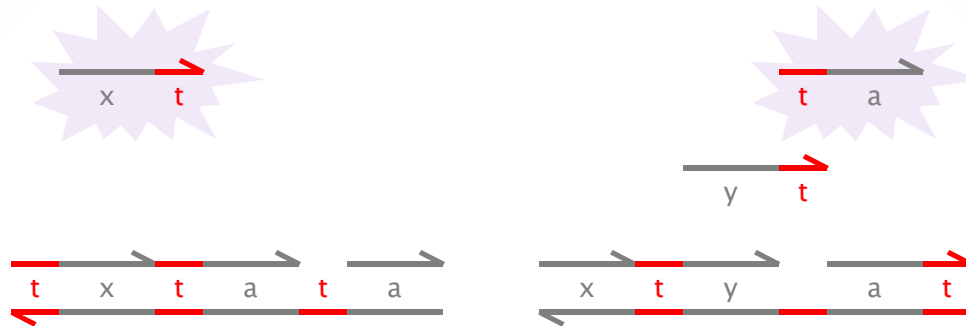


So far, a  $tx$  *signal* has produced an  $at$  *cosignal*.  
But we want signals as output, not cosignals.

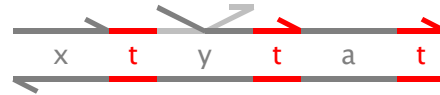
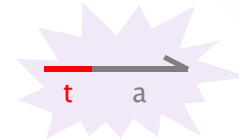
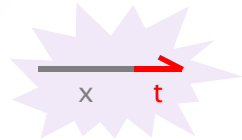
# Transducer $x \rightarrow y$



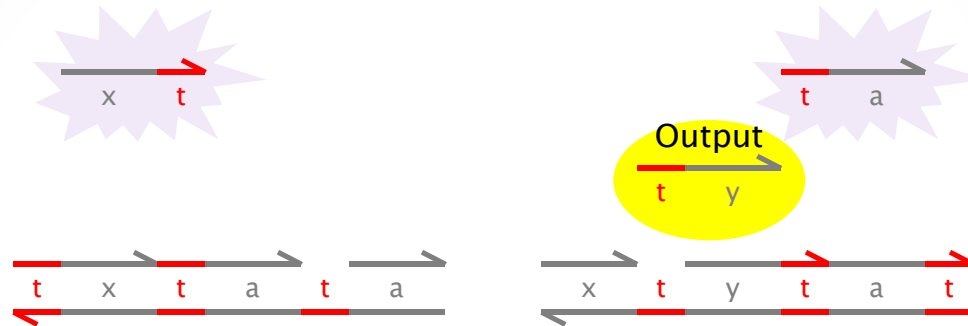
# Transducer $x \rightarrow y$



# Transducer $x \rightarrow y$



# Transducer $x \rightarrow y$



Here is our output **ty** *signal*.

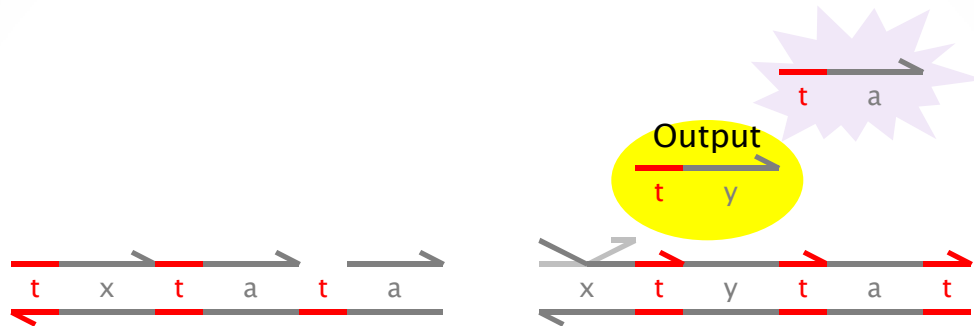
But we are not done yet:

- 1) We need to make the output irreversible.
- 2) We need to remove the garbage.

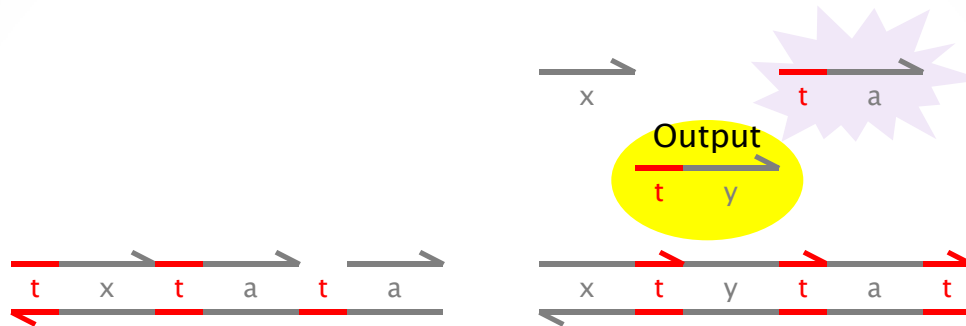
We can use (2) to achieve (1).



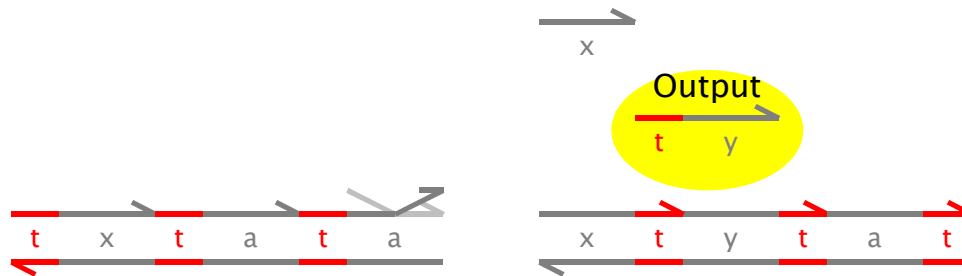
# Transducer $x \rightarrow y$



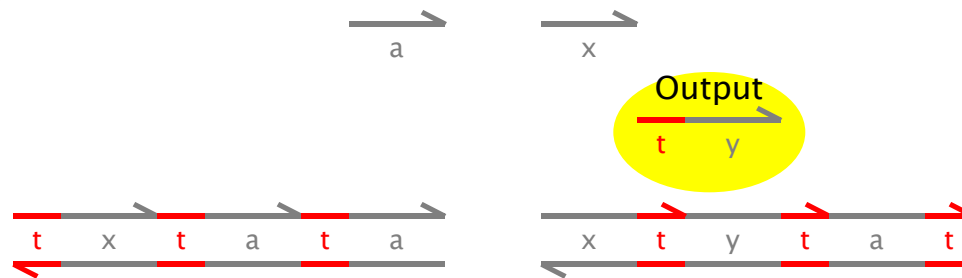
# Transducer $x \rightarrow y$



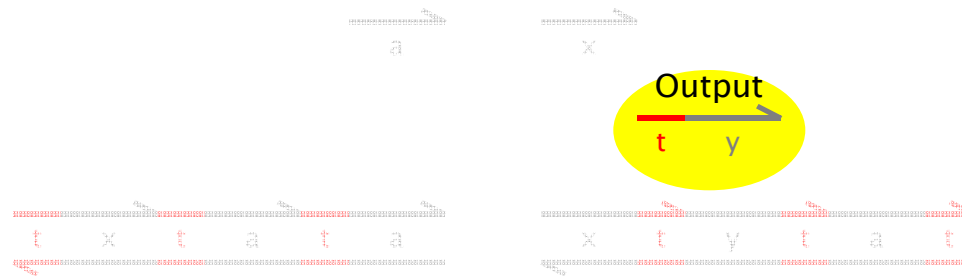
# Transducer $x \rightarrow y$



# Transducer $x \rightarrow y$



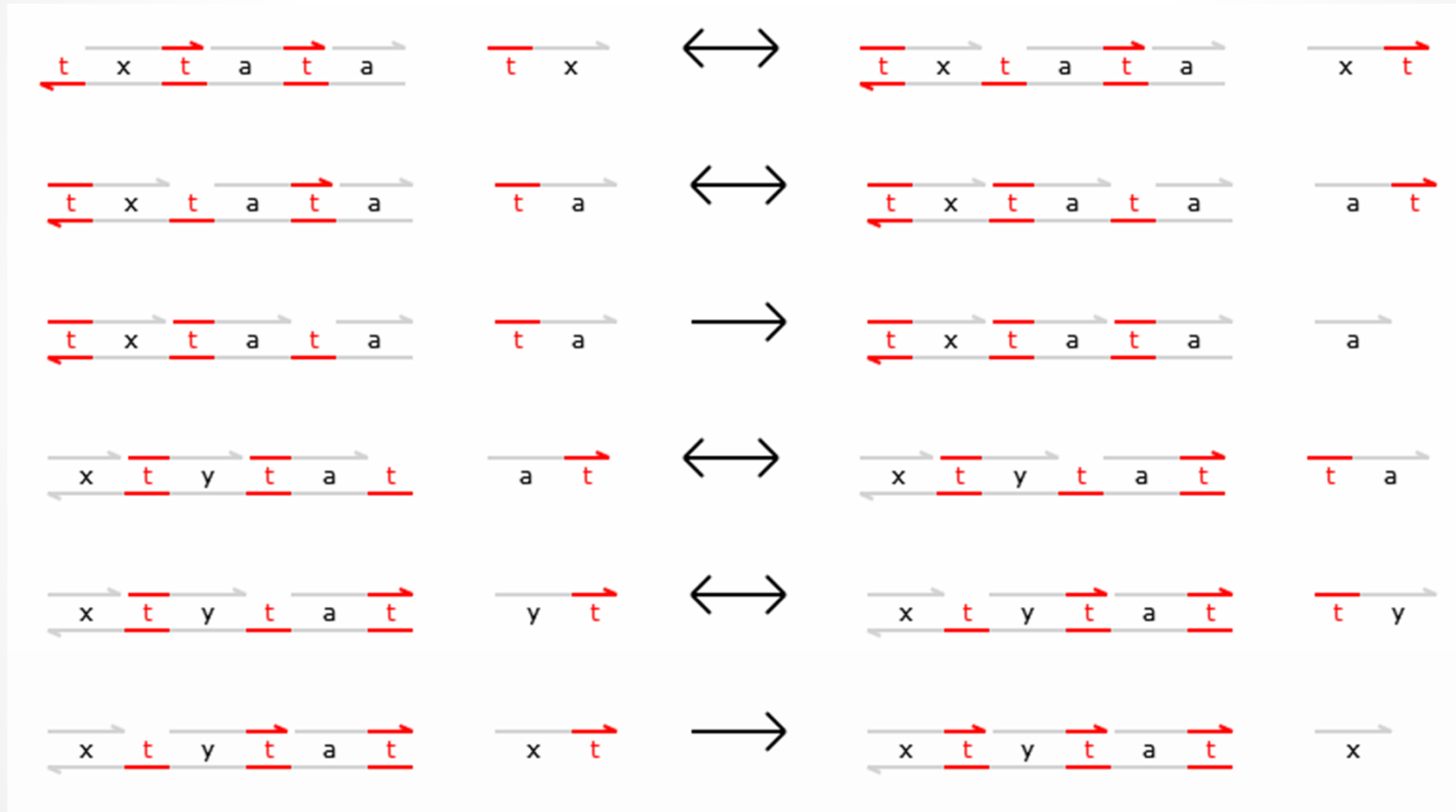
# Transducer $x \rightarrow y$



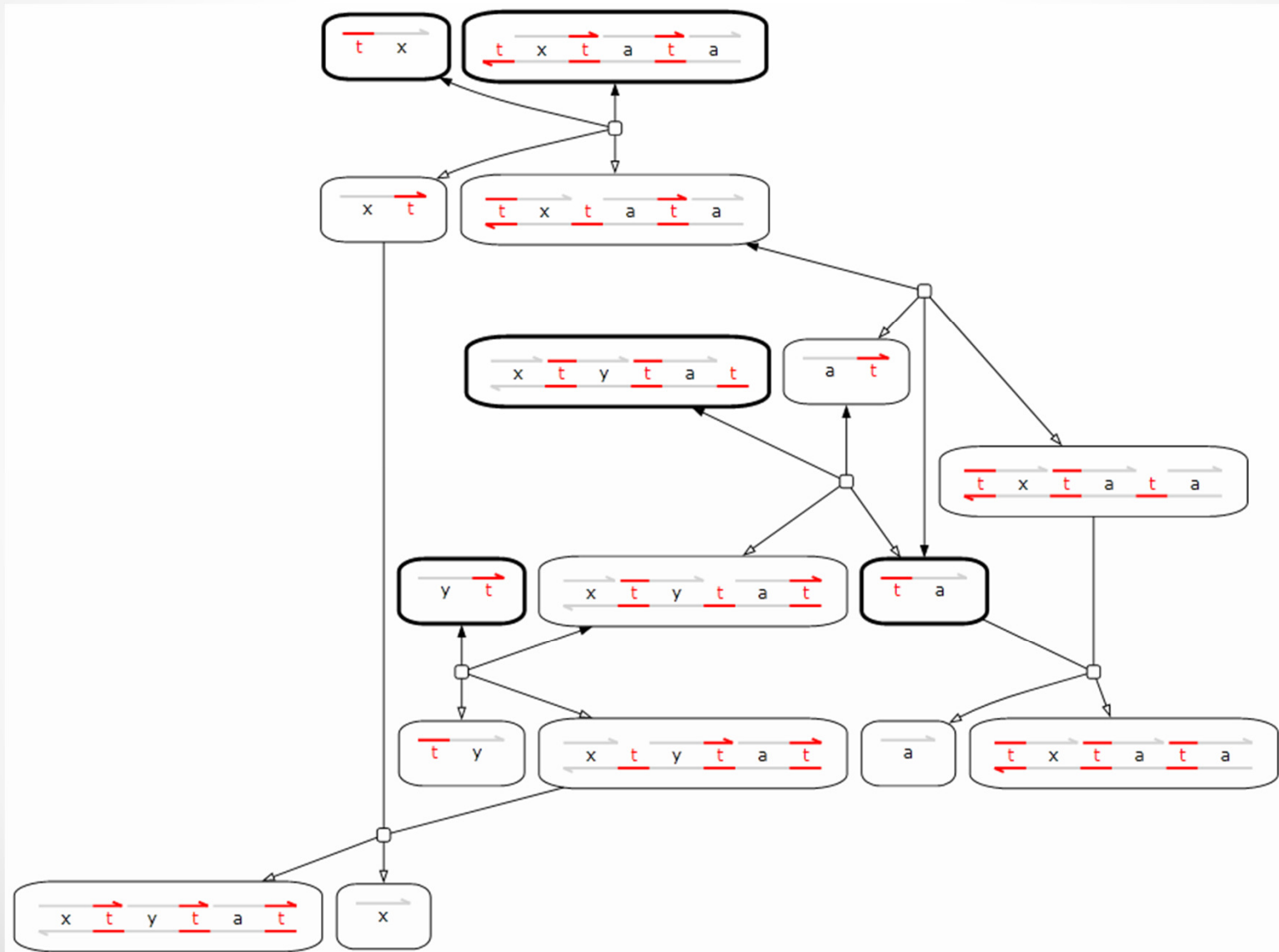
Done.

Note the **tata** motif and how it helps in collection.

# Transducer Reactions



# Transducer Reaction Graph



# Transducer Simulation

Examples:    Rules:  Simulation:  View options:     Leaks:  Domains:  v0.12-20100408-1540

Code

Zoom

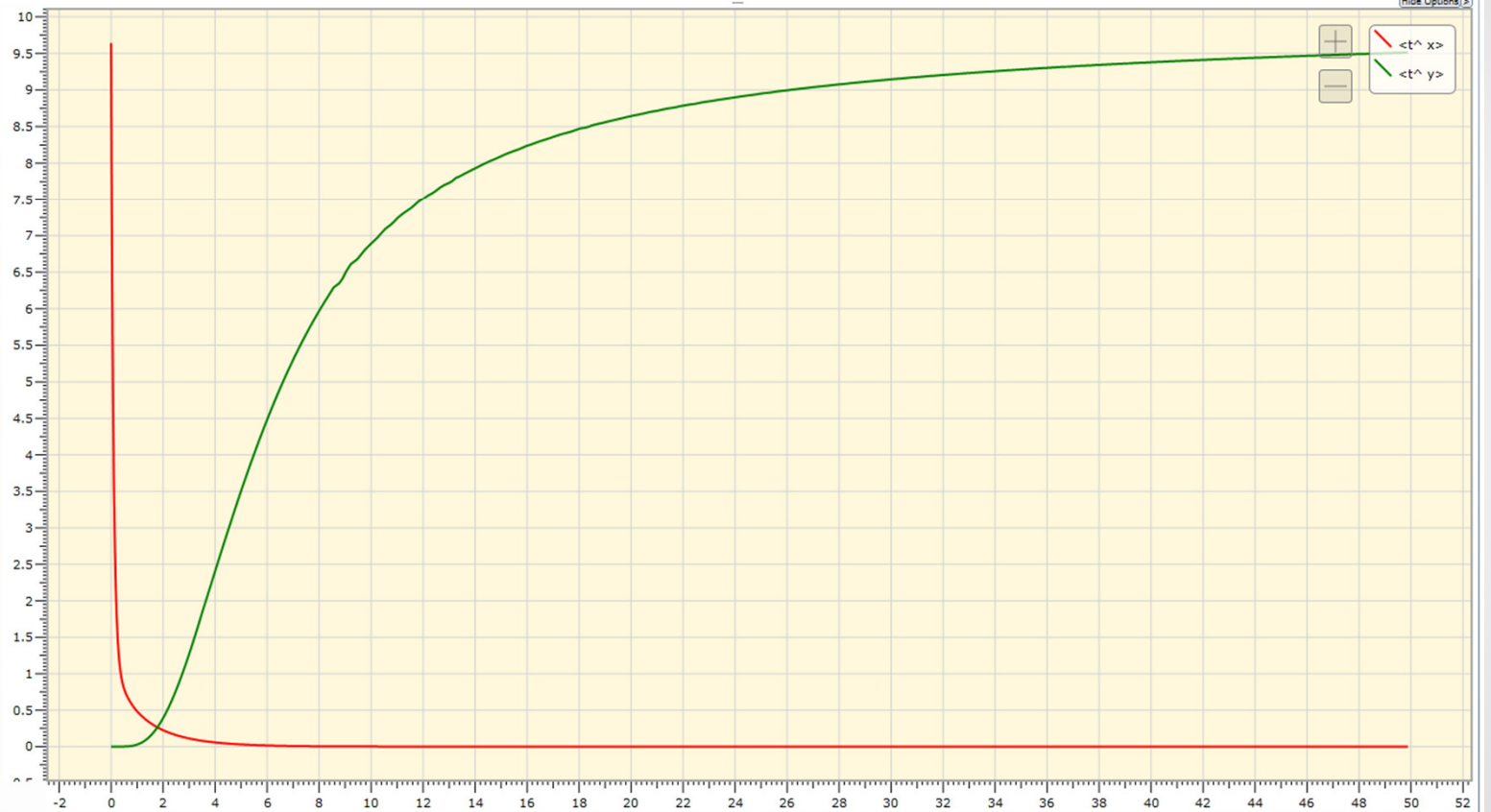
```
directive sample 50.0
directive plot <t^ x> <t^ y>
directive scale 1.0
new t@1.0,1.0

def Tr(N, x, y) =
  new a
  ( N* <t^ a>
  | N* <y t^>
  | N* t^:[x t^]:[a t^]:[a]
  | N* [x]:[t^ y]:[t^ a]:t^
  )

( Tr(10, x, y)
| 1* <t^ x>
)
```

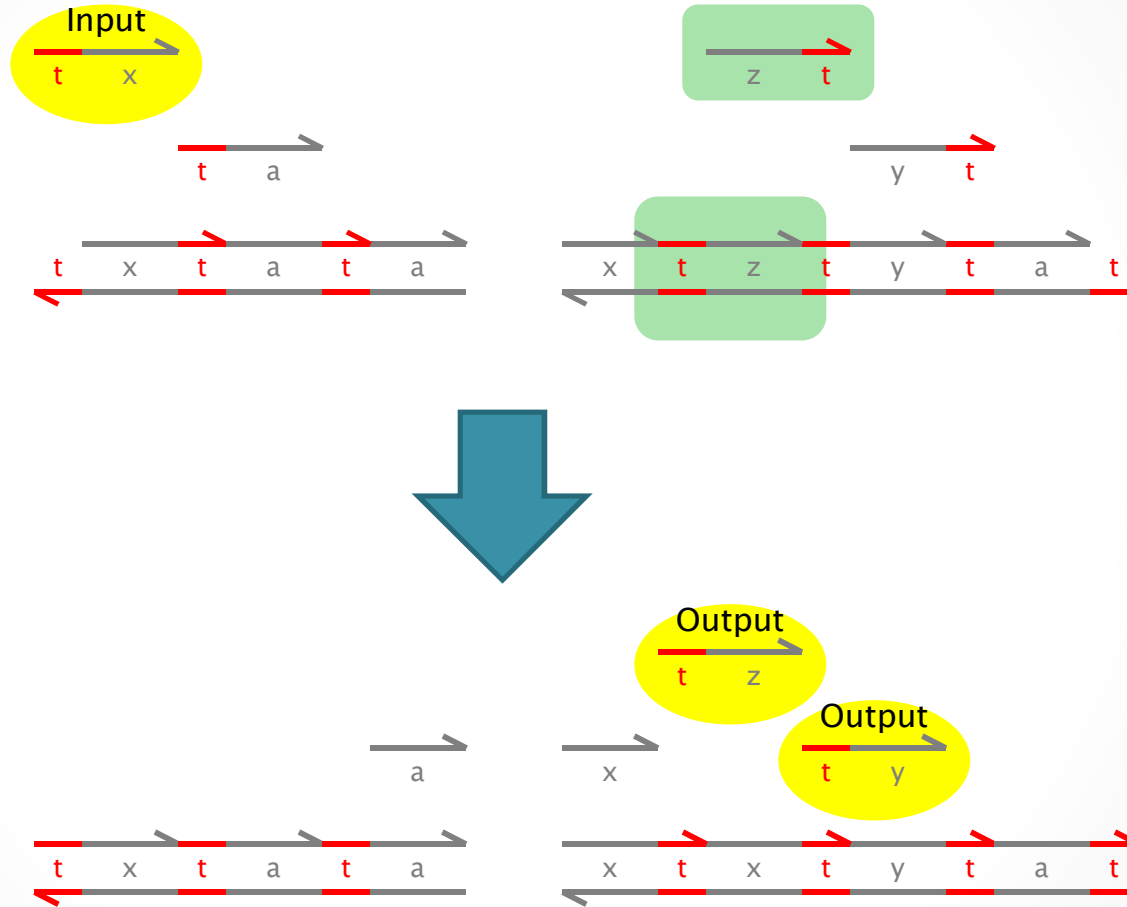
Species Reactions Graph Text SBML Domains Table Plot

Show all Hide all  <t^ x>  <t^ y>



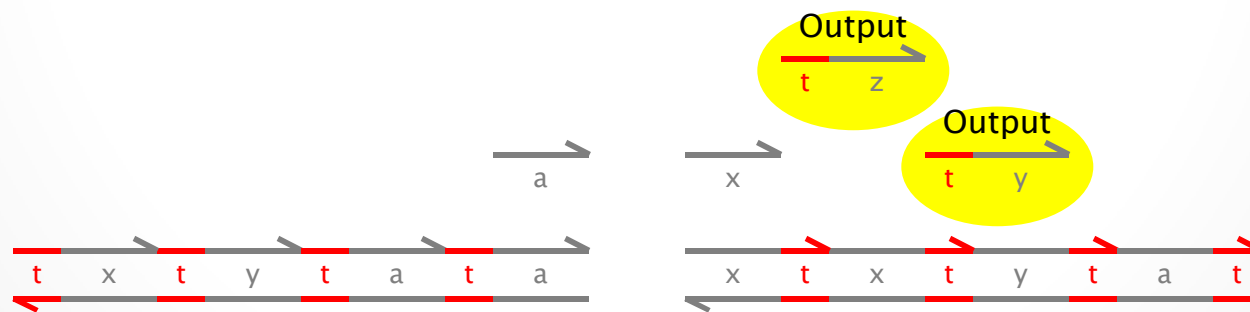
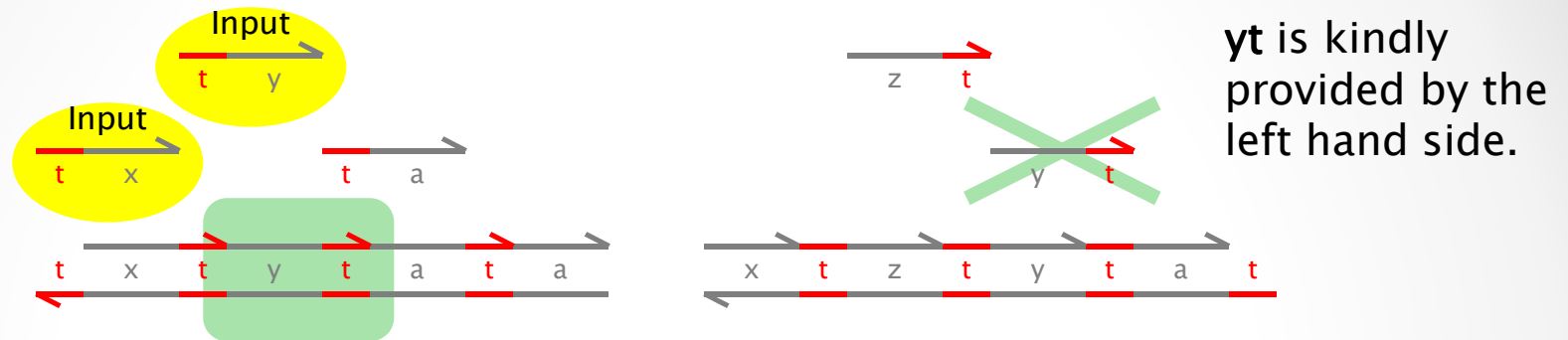


# Fork $x \rightarrow y+z$



(Amplifier:  $x \rightarrow x+x$ )

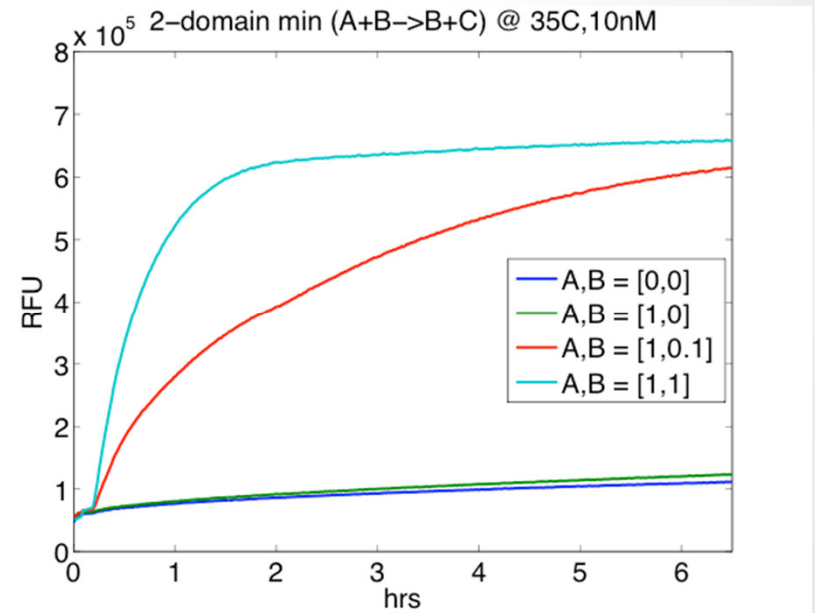
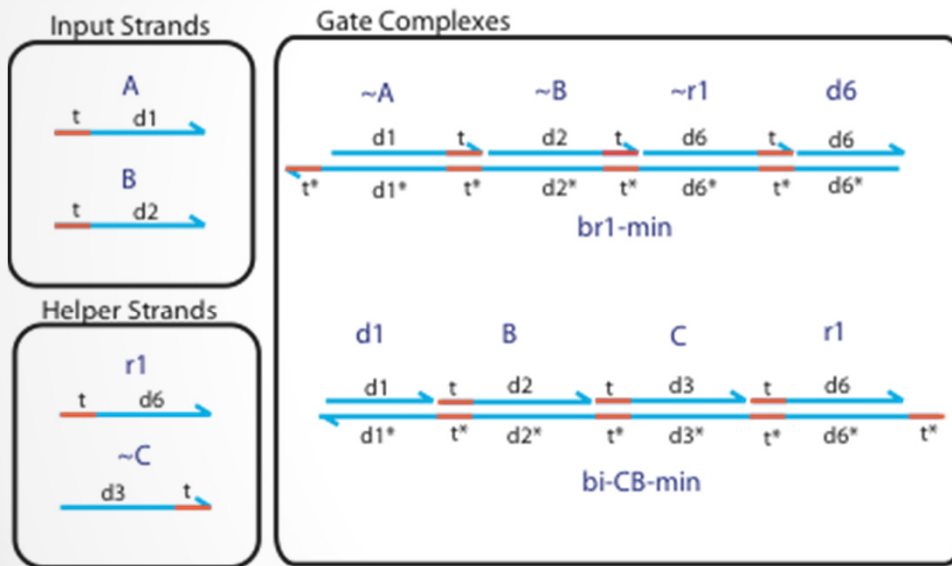
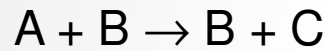
# Catalyst $x + y \rightarrow y + z$



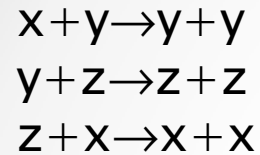
(Autocatalyst:  $x + y \rightarrow y + y$ )

# Experiments

Georg Seelig, Matt Olson



# Autocatalytic Oscillator



```

directive sample 100.0 1000
directive plot <t^ x>; <t^ y>;
<t^ z>
(* directive scale 100.0 *)

```

```
new t@1.0,100.0
```

```

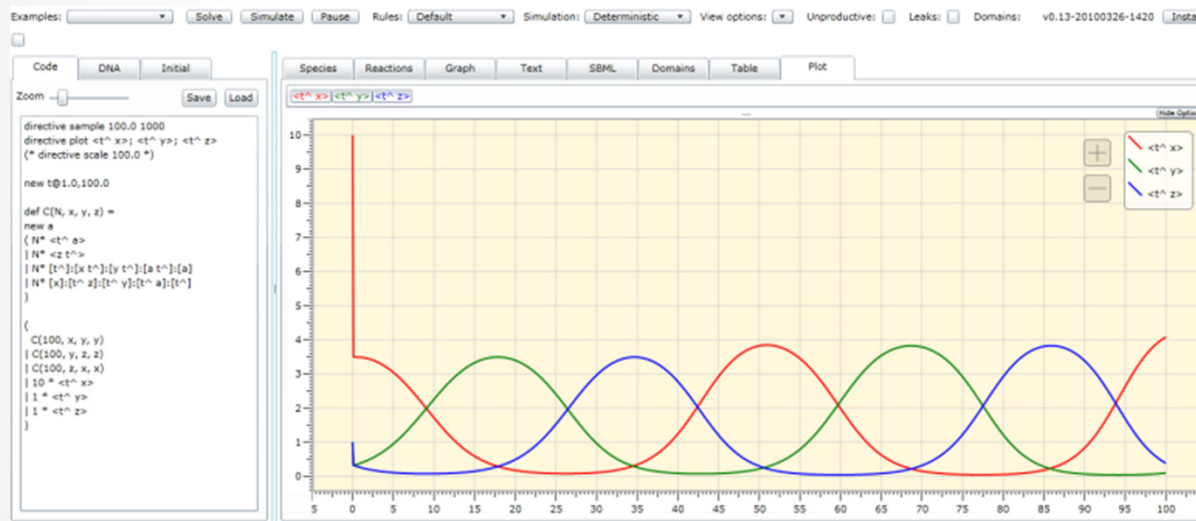
def C(N, x, y, z) =
new a
(N* <t^ a>
| N* <z t^>
| N* [t^]:[x t^]:[y t^]:[a t^]:[a]
| N* [x]:[t^ z]:[t^ y]:[t^ a]:[t^]
)

```

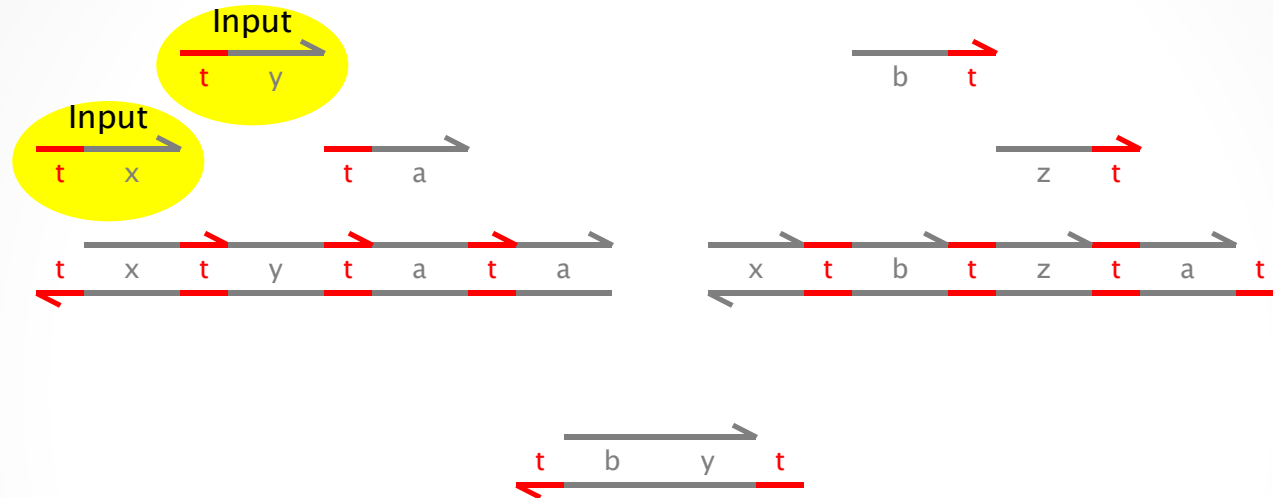
```

(
C(100, x, y, y)
| C(100, y, z, z)
| C(100, z, x, x)
| 10 * <t^ x>
| 1 * <t^ y>
| 1 * <t^ z>
)

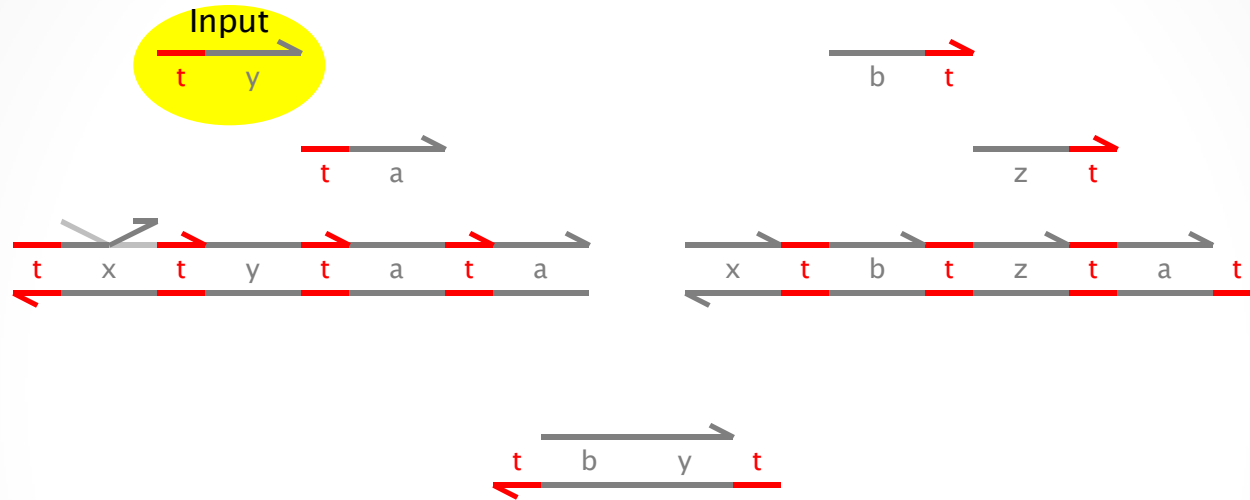
```



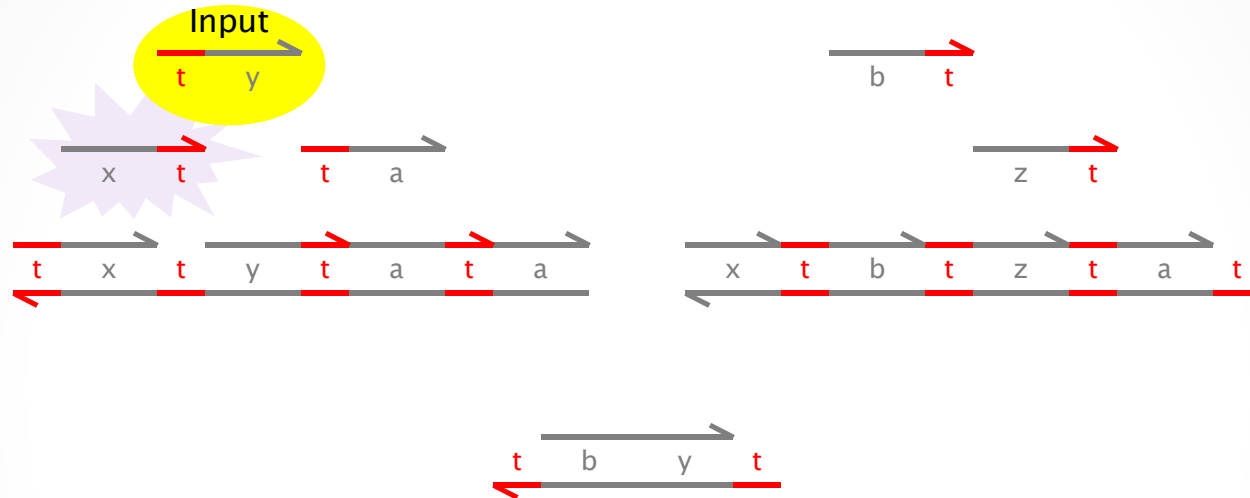
# Join $x+y \rightarrow z$



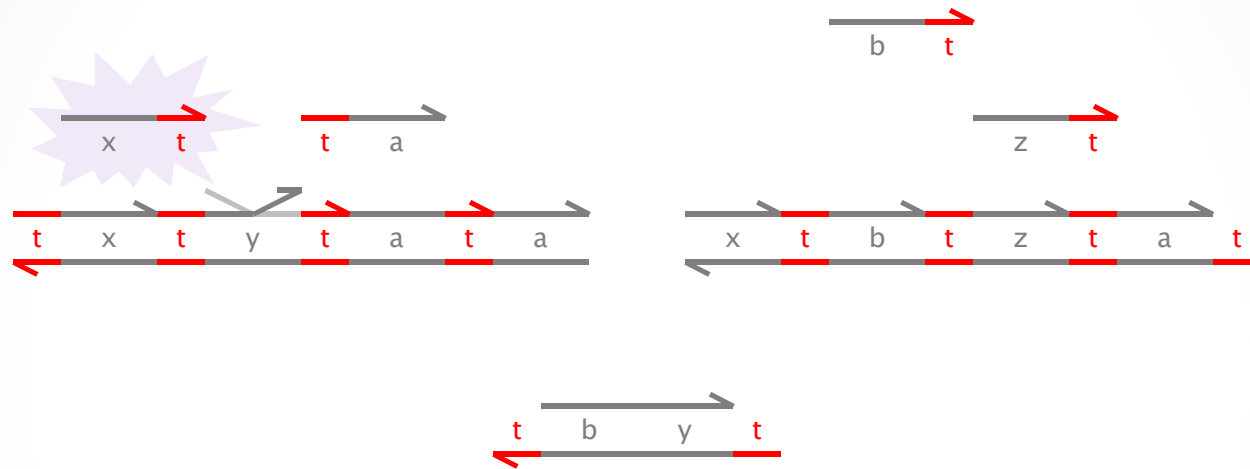
# Join $x+y \rightarrow z$



# Join $x+y \rightarrow z$

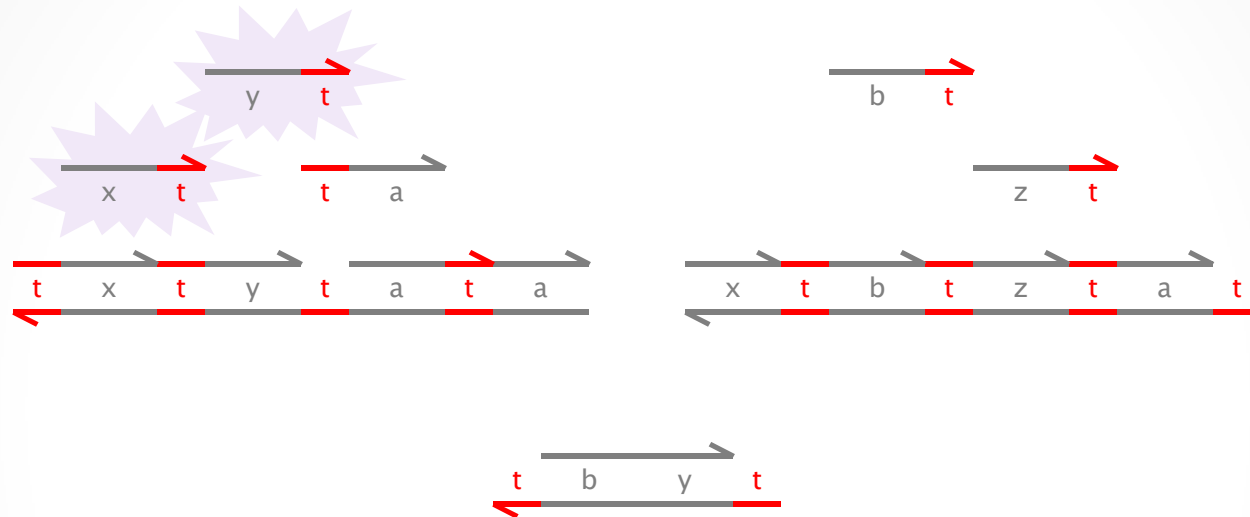


# Join $x+y \rightarrow z$





# Join $x+y \rightarrow z$



We cannot have a collector just waiting for  $yt$ , because there may be innocent  $yt$  elsewhere in the system, like here!

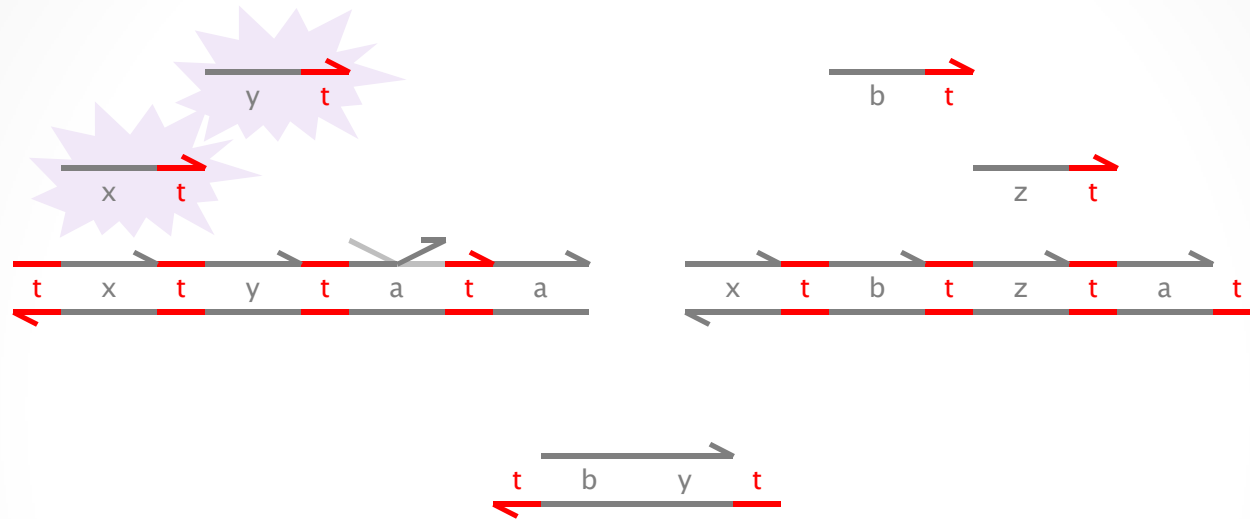


Transducer  $x \rightarrow y$

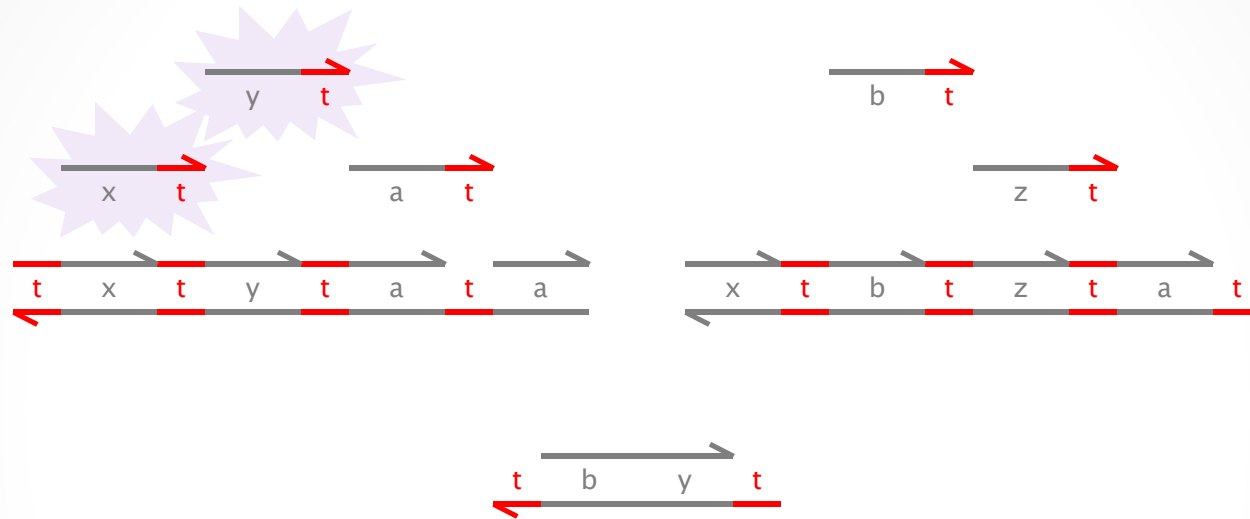
Instead, the collection of  $yt$  must be triggered only by a signal signifying that an  $x+y \rightarrow z$  gate has fired. That signal is  $tb$ , which will trigger the collection of  $yt$  after output  $tz$  is produced.

$bt$  is a *private* signal (a different 'b' for each  $xyz$  triple)

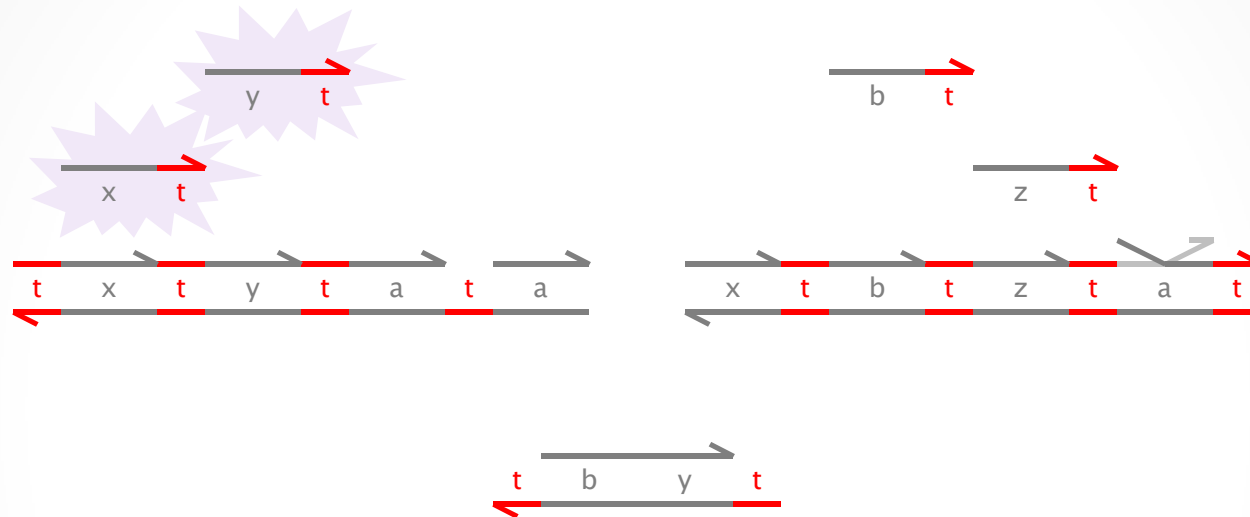
# Join $x+y \rightarrow z$



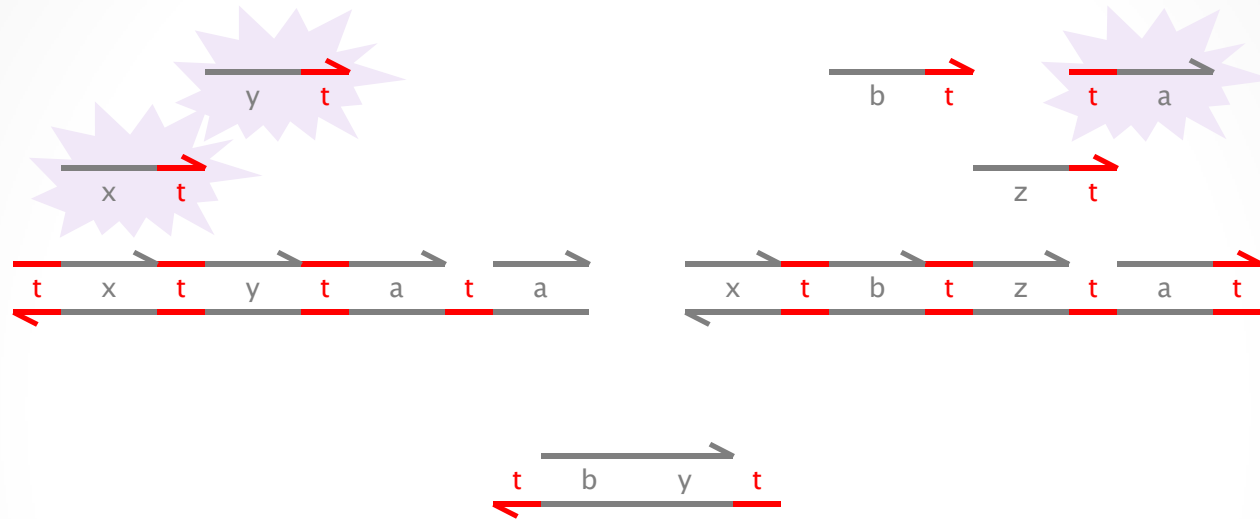
# Join $x+y \rightarrow z$



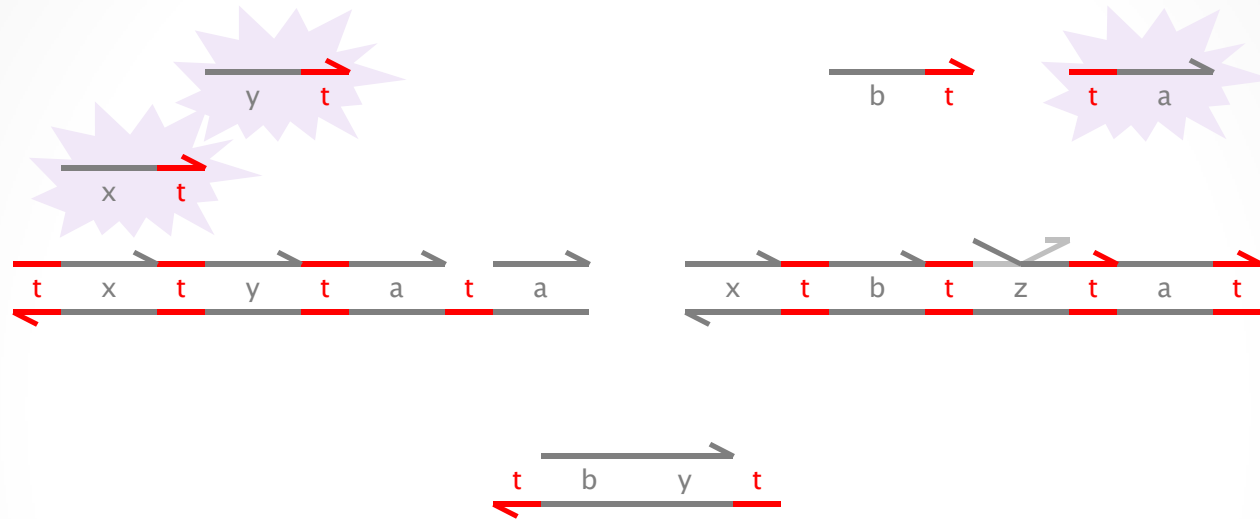
# Join $x+y \rightarrow z$



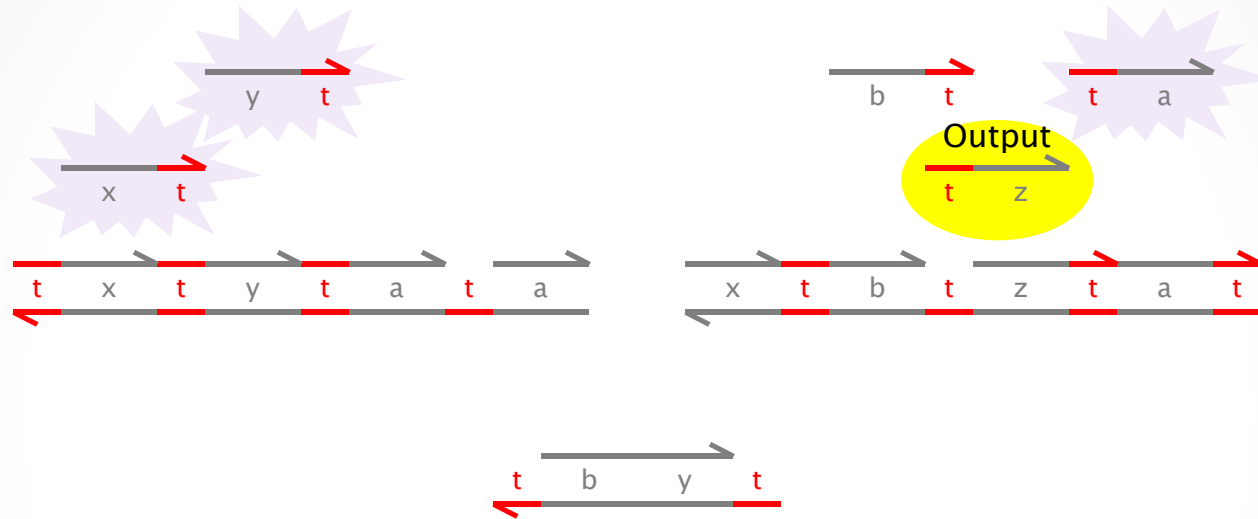
# Join $x+y \rightarrow z$



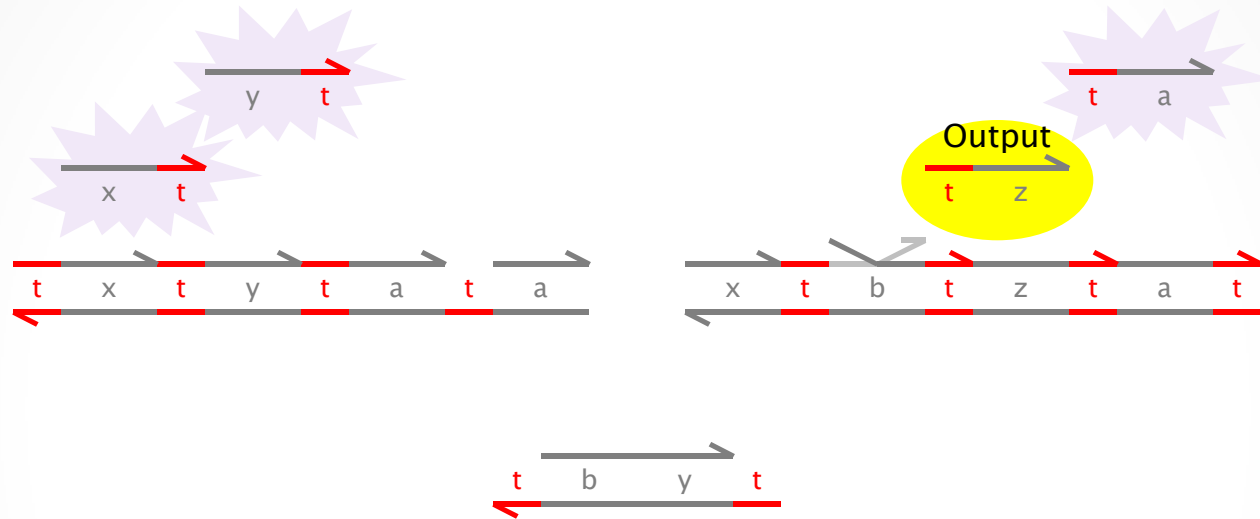
# Join $x+y \rightarrow z$



# Join $x+y \rightarrow z$

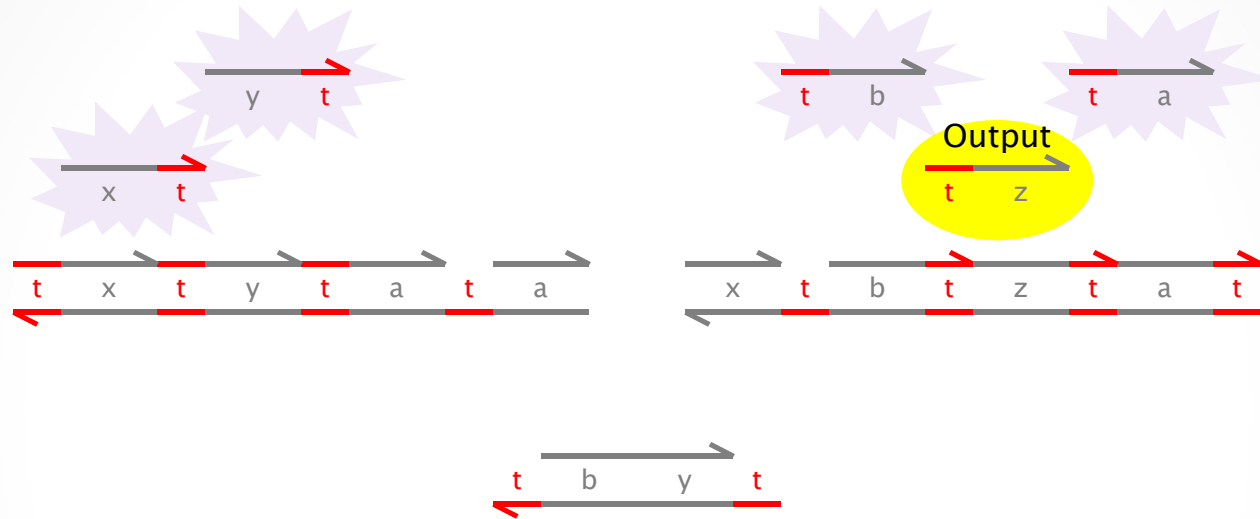


# Join $x+y \rightarrow z$

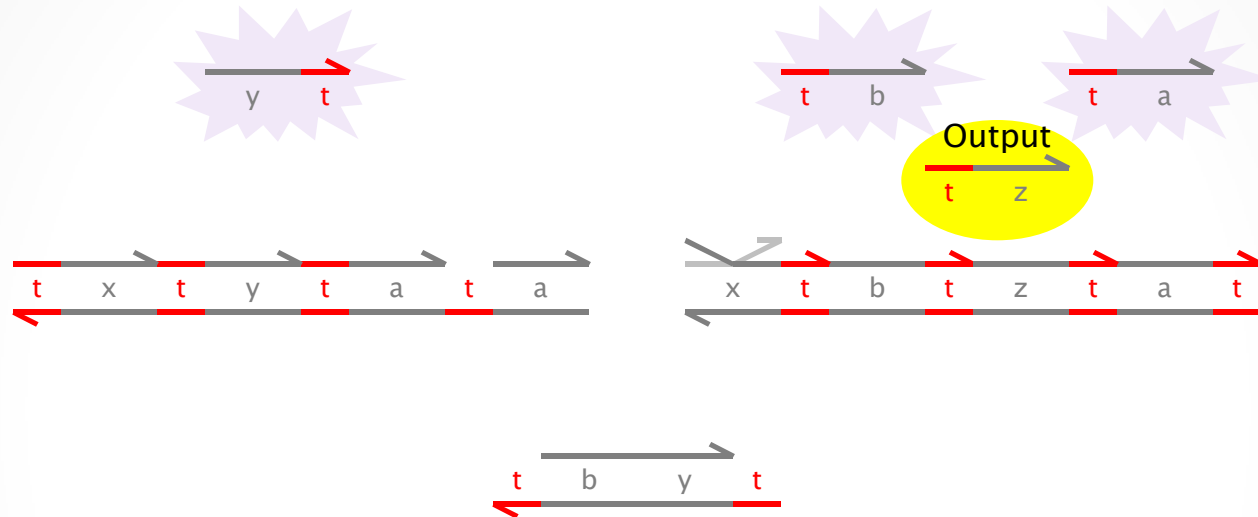




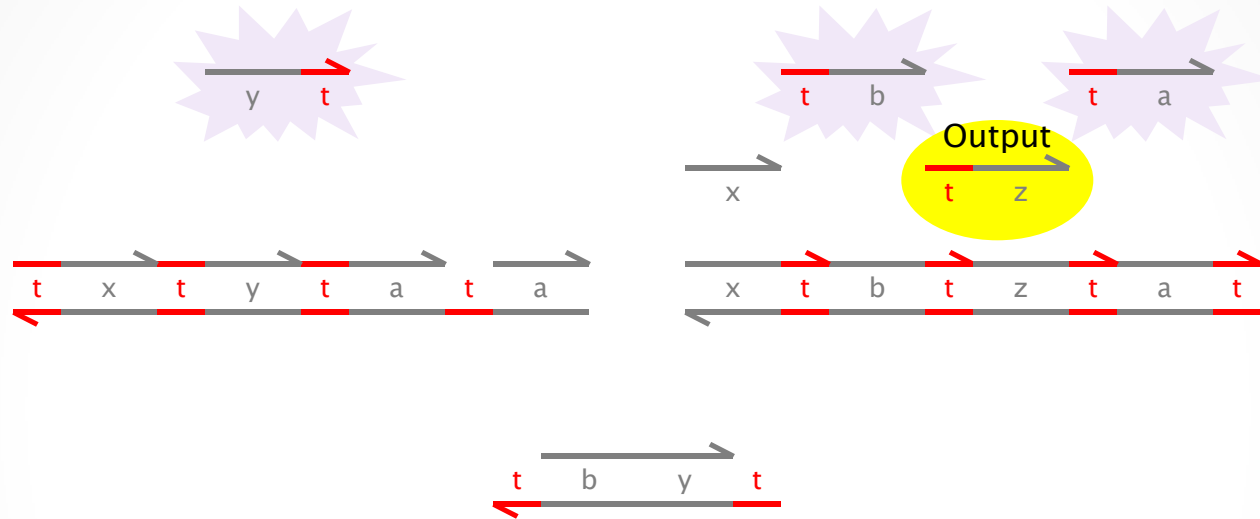
# Join $x+y \rightarrow z$



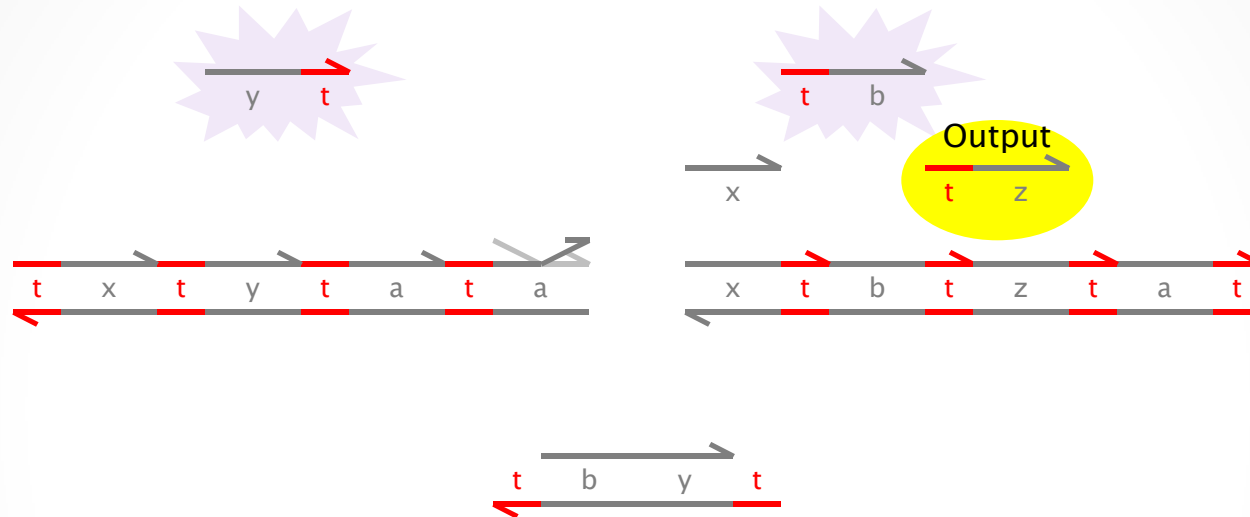
# Join $x+y \rightarrow z$



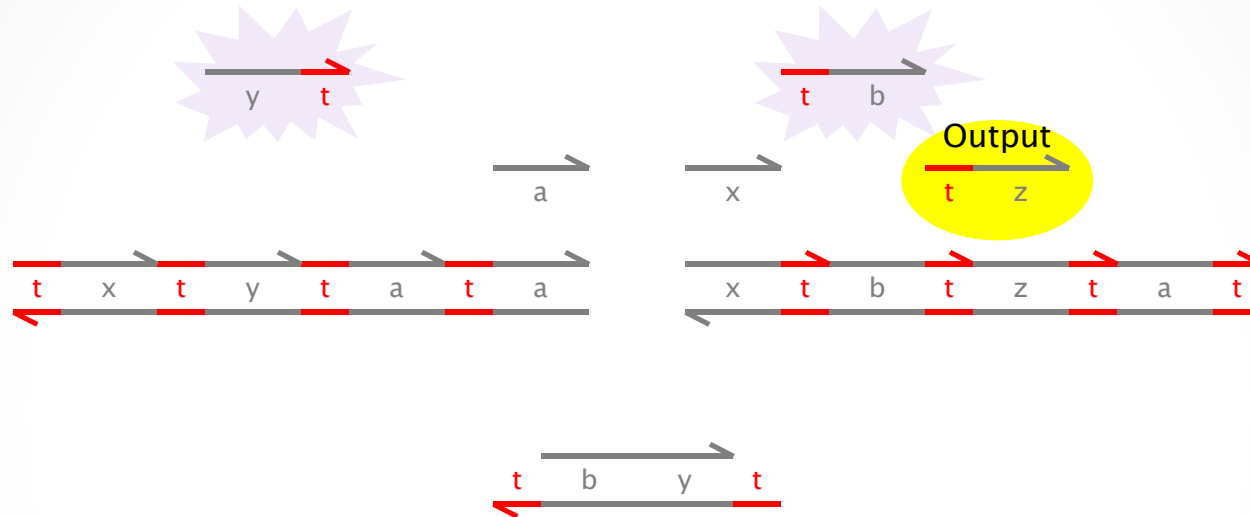
# Join $x+y \rightarrow z$



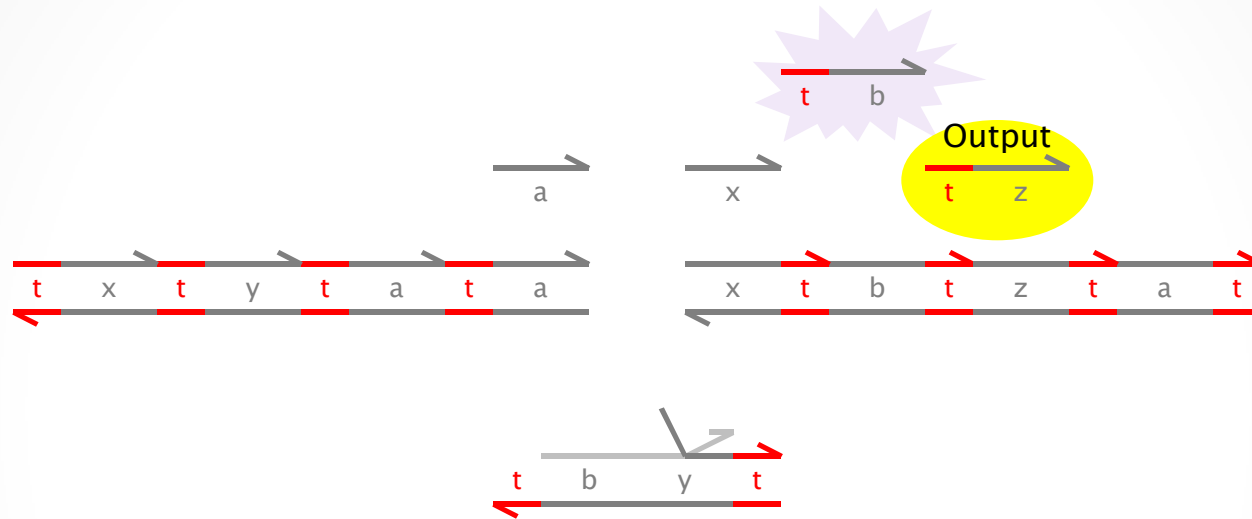
# Join $x+y \rightarrow z$



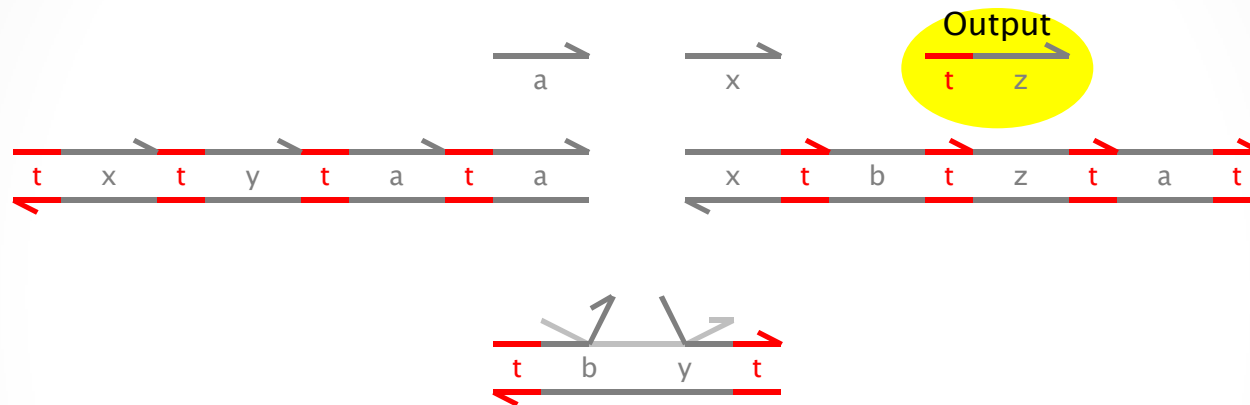
# Join $x+y \rightarrow z$



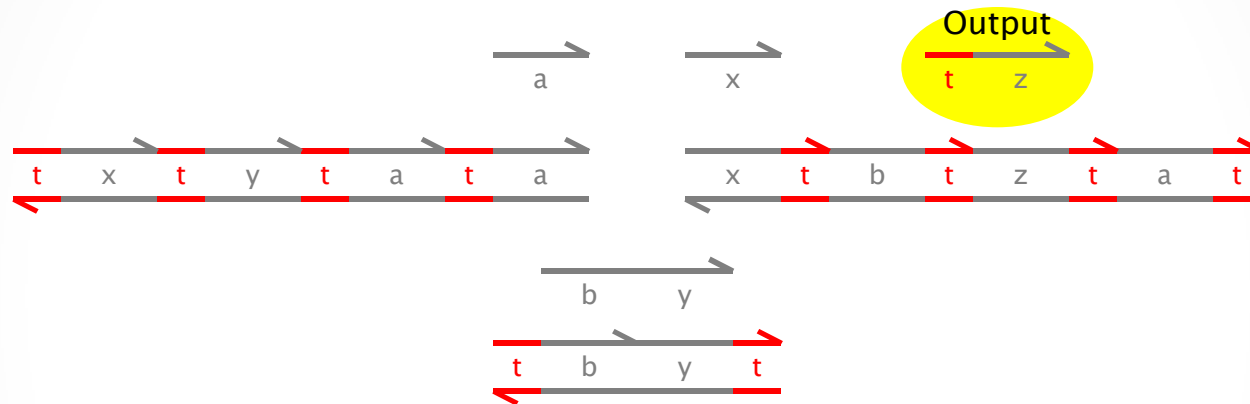
# Join $x + y \rightarrow z$



# Join $x+y \rightarrow z$



# Join $x+y \rightarrow z$





# General $n \times m$ Join-Fork

- Easily generalized to 3+ inputs (with 2+ collectors) etc.
- Easily generalized to 2+ outputs (like Fork) etc.

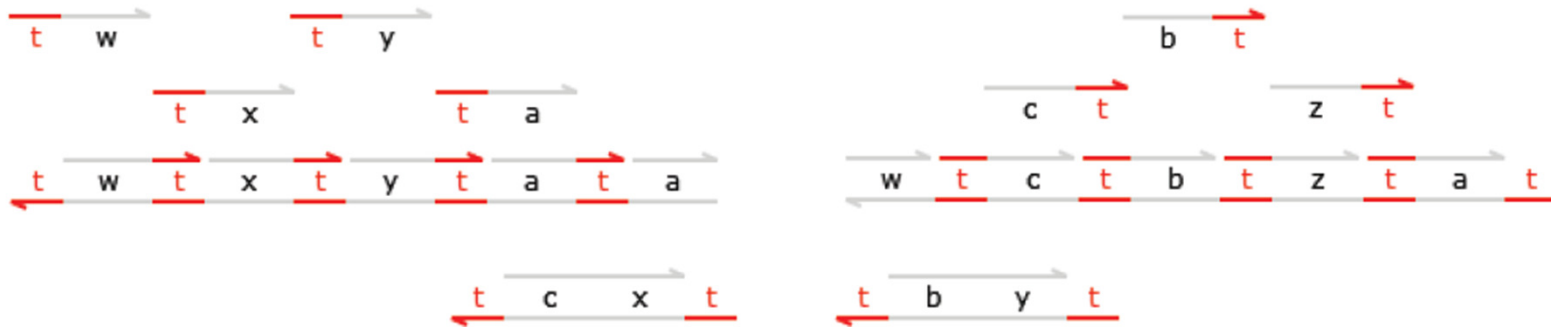
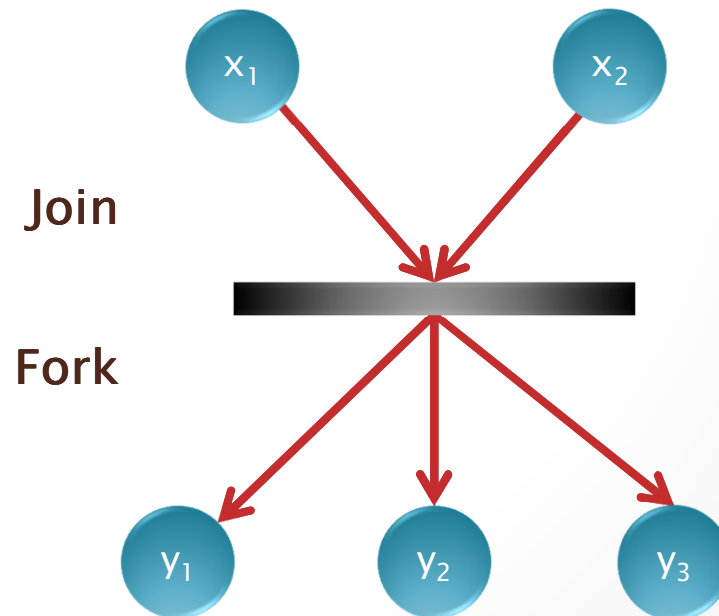


Figure 9: 3-Join  $J_{wxyz} \mid tw \mid tx \mid ty \rightarrow tz$ : initial state plus inputs  $tw, tx, ty$ .

# Petri Net Transitions

- Computing power equivalent to Petri Nets (not Turing complete).
- Not completely trivial: gates are consumed by activation, hence a persistent Petri net transition requires a stable population of gates.



# Verification

...

# Verification Issues

- Individual Components

- Reversible reactions (infinite traces)
- Interferences (deadlocks etc.) between copies of the same gate
- Interferences (deadlocks etc.) between copies of different gates
- Removal of active byproducts (garbage collection) is tricky

- Populations

- Gates come in (large) populations
- Each population *shares private domains* (technologically unavoidable)
- Correctness of populations means proofs with large state spaces
- Proofs about *arbitrary* population size?

- Environment

- The nano-environment is stochastic (noise, failures, etc.)
- Biology is messy
- But we should at least make sure our designs are *logically correct*

# Correctness

- The spec of a transducer:  $T_{xy} + tx \rightarrow ty$ 
  - Is it true at all?
  - Is it true *possibly*, or *necessarily*, or *probabilistically (measure 1)*?
  - Is it true in the context of a *population of identical transducers*?
  - Is it true *in all possible contexts*?
  - Is it *(more)* true for large populations?
  - Is it true for infinite populations (continuous limit)?

Nick Algebra

...

# Nick Algebra

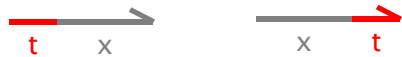
$S ::= t.x \mid x.t$

$\underline{D} ::= \emptyset \mid \underline{t} \mid \underline{x} \mid \underline{t.x} \mid \underline{x.t} \mid \underline{x.x} \mid \underline{D^+D}$

$U ::= S \mid \underline{D} \mid U|U \mid (vx)U$

single strand  
double strand  
soup

$S$



nick operator

$\underline{D}$



# Reduction

$$\underline{D}_1 \dagger \underline{t \dagger x \dagger t} \dagger \underline{D}_2 \mid tx \leftrightarrow \underline{D}_1 \dagger \underline{tx \dagger t} \dagger \underline{D}_2 \mid xt$$

exchange

$$\underline{D}_1 \dagger \underline{t \dagger x} \dagger \underline{D}_2 \mid tx \rightarrow \underline{D}_1 \dagger \underline{tx} \dagger \underline{D}_2$$

left coverage

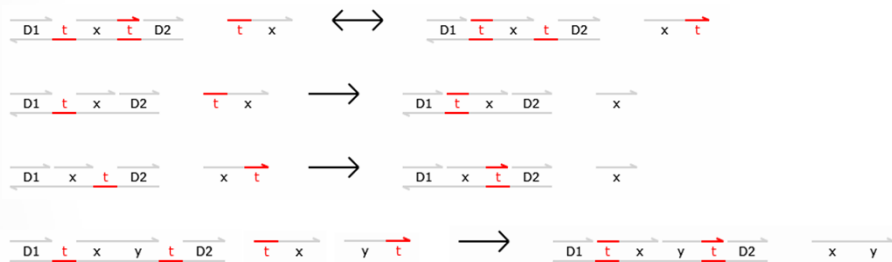
$$\underline{D}_1 \dagger \underline{x \dagger t} \dagger \underline{D}_2 \mid xt \rightarrow \underline{D}_1 \dagger \underline{xt} \dagger \underline{D}_2$$

right coverage

$$\underline{D}_1 \dagger \underline{t \dagger xy \dagger t} \dagger \underline{D}_2 \mid tx \mid yt \rightarrow \underline{D}_1 \dagger \underline{tx \dagger yt} \dagger \underline{D}_2$$

cooperation

i.e.:



$$\underline{D} \rightarrow \emptyset \quad \text{if } \underline{D} \text{ not reactive} \quad \text{waste}$$

$$U_1 \rightarrow U_2 \Rightarrow U_1 \mid U \rightarrow U_2 \mid U \quad \text{dilution}$$

$$U_1 \rightarrow U_2 \Rightarrow (vx)U_1 \rightarrow (vx)U_2 \quad \text{isolation}$$

$$U_1 = U_2, U_2 \rightarrow U_3, U_3 = U_4 \Rightarrow U_1 \rightarrow U_4 \quad \text{mixing}$$



# Reachability

- $U_1 \rightarrow^* U_2$  iff  $U_1 \rightarrow \dots \rightarrow U_2$ 
  - That is,  $U_1$  *may* reduce to  $U_2$ .
- $U_1 \rightarrow^\forall U_2$  iff  $\forall U, U_1 \rightarrow^* U \Rightarrow U \rightarrow^* U_2$ 
  - That is,  $U_1$  *will* reduce to  $U_2$ . (It cannot avoid the possibility of reducing to  $U_2$ ).
  - $U \rightarrow^\forall U$  means that  $U$  is *reversible*.
  - If  $U_2$  is the only terminal state then  $U_1 \rightarrow^\forall U_2$  means that  $U_1$  *must* reduce to  $U_2$ .

# Gate Definitions

- $T_{xay} = \underline{t^\dagger x t^\dagger a t^\dagger a} \mid ta \mid \underline{x^\dagger t y^\dagger t a^\dagger t} \mid yt$
- $T_{xy}^n = (va)((T_{xay})^n)$
  
- $F_{xayz} = \dots$
- $F_{xyz}^n = (va)((F_{xayz})^n)$
  
- $J_{xyaz} = \dots$
- $J_{xyz}^n = (va)((J_{xyaz})^n)$

# Correctness

- **Proposition: May-Correctness**

$$T^n_{xy} | tx^n \rightarrow^* ty^n$$

$$F^n_{xyz} | tx^n \rightarrow^* ty^n | tz^n$$

$$J^n_{xyz} | tx^n | ty^n \rightarrow^* tz^n$$

- Easy case analysis and induction on n.

- **Proposition:  $T^1_{xy}$  Will-Correctness**

$$T^1_{xy} | tx \rightarrow^{\forall} ty$$

- Exhaustive case analysis enumerating all states of the system.
- Can be done by hand for  $T^1_{xy}$ , and maybe  $T^2_{xy}$ , but not really for  $T^3_{xy}$  etc.
- Will-correctness for fork/join is harder (more states).
- Will-correctness for combinations of gates is harder (does not compose and requires analysis of joint state space).
- We are using modelchecking to verify some of these properties.  
[Andrew Phillips & David Parker in PRISM]

# Interfering Transducers

- Although  $T_{xay} \mid T_{yax} \mid tx \not\rightarrow^{\forall} tx$
- We have  $T_{xay} \mid T_{yax} \mid tx \mid ty \rightarrow^{\forall} tx \mid ty$
- That means that a large population of such gates in practice does not deadlock easily: each pair of deadlocked gates can be unblocked by another pair correctly producing a  $ty$  as an intermediate product.
- **Wisdom of the masses**: individuals can be wrong, but the population is right. It is very unlikely that a significant fraction of gates ends up being deadlocked.

# Conclusions

- A new architecture for general DNA gates
  - Simple signals, simple gate structures.
  - Self-cleaning: no garbage left by operation (except inert).
  - Enabling new ways of assembling gates.
  - Some experimental evidence that it works.
- A correspondingly simple algebra
  - For verifying gate designs mechanically.
- Verification issues
  - Verification techniques for gate populations.
  - Are the fork/join gates in Nick Algebra a correct implementation of (Strand Algebra and) Petri nets?